Reactive Systems: The Why and the How

CJUG May 19, 2015 dean.wampler@typesafe.com @deanwampler

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Tuesday, May 19, 15

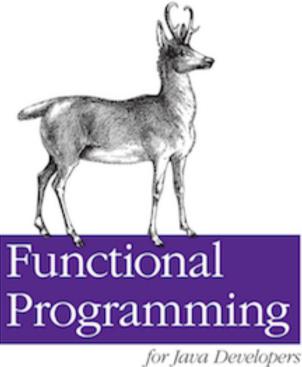
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Dean Wampler

Chicago User Groups



Chicago Area Scala Enthusiasts Spark Spark Users Chicago Area Hadoop User Group

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I founded CASE, I lead the Spark Users group, and I'm a co-organizer of CHUG.



Motivation:

eCommerce

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Let's motivate the notion of "reactive" systems by exploring some common scenarios we see today.

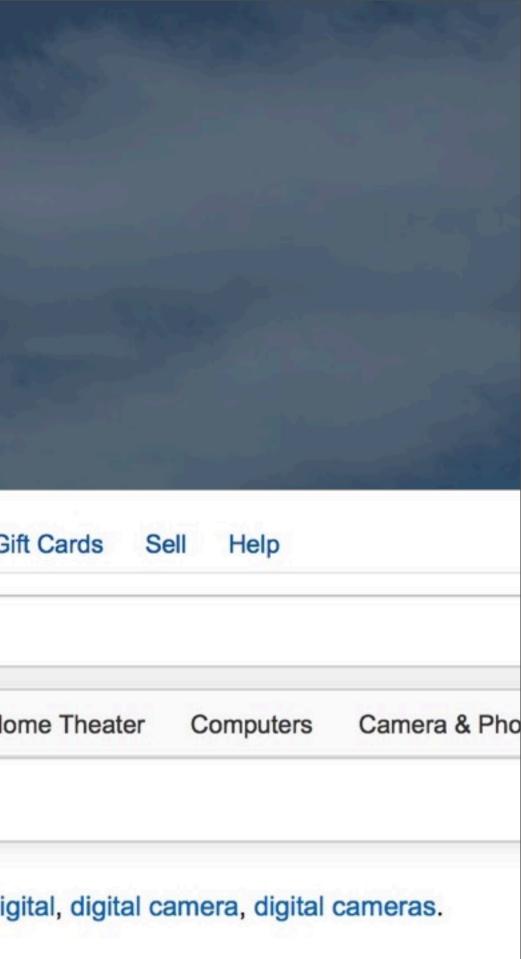


Cyber Monday?

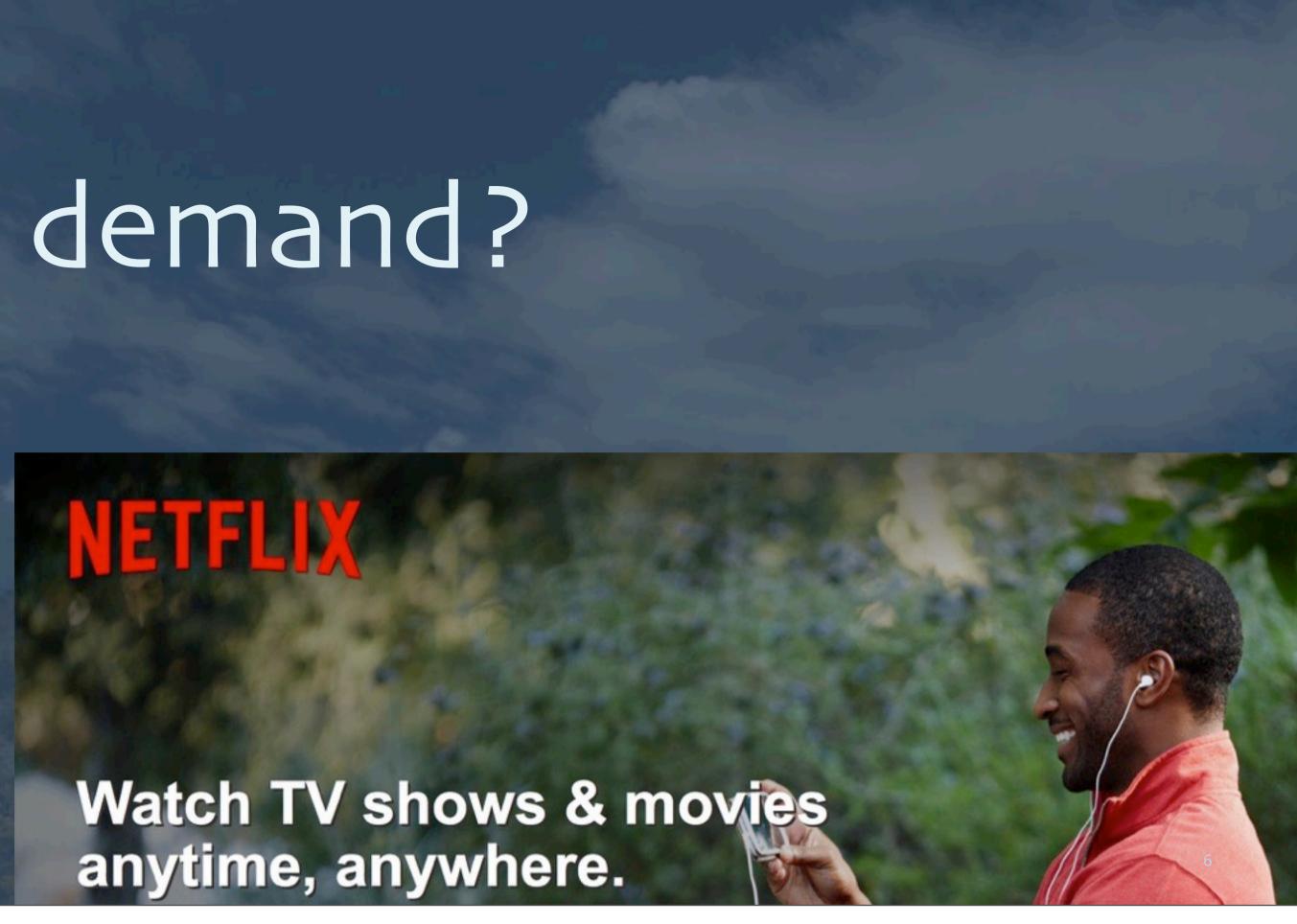
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Your online store needs to scale up and down with demand. It needs to degrade gracefully if some service components are lost or disconnected by a network partition. For example, if the canonical catalog "disappears" behind a network partition, it's probably better to continue selling with a stale local copy. photo: Amazon home page, <u>http://amazon.com</u>.



On demand?



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Netflix has extreme scale challenges, but they have become an innovator in building highly resilient, scalable services. What happens when a new season of "House of Cards" is released? Spikes in traffic? photo: Netflix home page, <u>http://netflix.com</u>.

Motivation:

Internet of Things

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Internet of Things has several categories of applications, each of which has needs that motivate reactive programming.



Medical Devices, IT Systems Phone home: • Upload data • Usage patterns Predictive diagnostics • Fetch patches

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Medical devices upload test results (e.g., ultrasound images and video) to servers. Med. devices and IT systems send requests for automated updates, send the equivalent of "click-stream" data used to assess usability, etc., and increasingly send metrics used to predict potential HW failures or other service needs. ultrasound photo: <u>http://www.usa.philips.com/healthcare-product/HC795054/hd11-xe-ultrasound-system</u> switch photo: <u>http://networklessons.com/switching/introduction-to-vtp-vlan-trunking-protocol/</u>



Medical Devices, IT Systems Characteristics: • Stable to intermittent network connectivity One way and two way Mixed bandwidth

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A mobile scanner might move in and out of WiFi zones, so caching data is necessary. IT appliances are (hopefully) always online. Some data is one way, like diagnostic info for predictive analytics, while data uploads and patch requests need acknowledgements. Bandwidth can vary.



Aircraft Engines

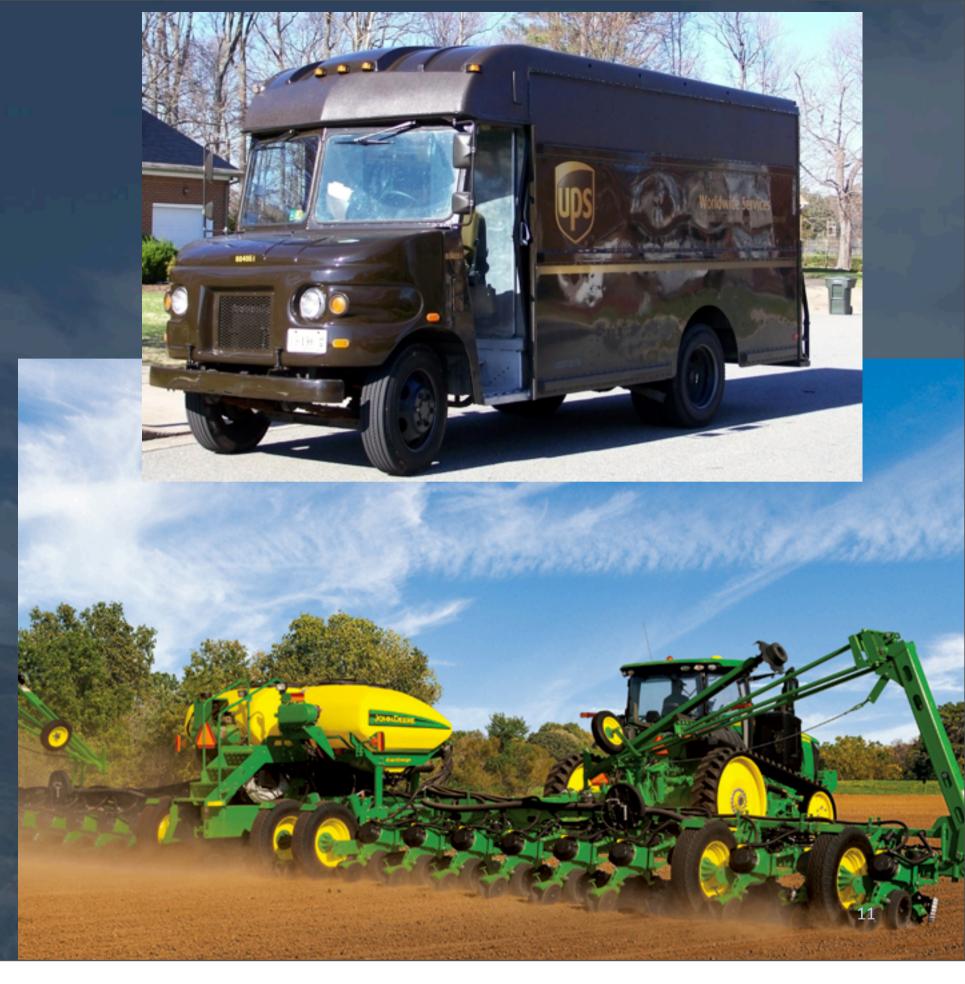
Phone home: • Upload telemetry Predictive diagnostics • Redundant tracking data!



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Each engine collects 0.5-1TB of data per flight. Most is currently tossed! Our only clue about the final resting place of Malaysian Airlines Flight 370 was engine telemetry picked up by satellites and used to analyze possible routes.

Trucks, Farm Equipment GPS Tracking: • Optimize routing, fuel use, etc. • Spy on drivers? • Per plant tracking!



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Track data to optimize routing, minimize fuel use with shortest path and/or delivering heaviest items first. Ensure drivers are obeying the rules of the road and company policies. Some farm equipment planting, watering, and fertilizing gear now tracks data per plant! UPS truck photo: <u>http://en.wikipedia.org/wiki/United_Parcel_Service</u> Planter/seeder photo: <u>http://www.deere.com/en_US/products/equipment/planting_and_seeding_equipment/planting_and_seeding_equipment/planting_and_seeding_equipment/planting_and_seeding_equipment.page?</u> Trucks, Farm Equipment Connectivity: •Always along roads Intermittent on farms (WiFi in barns?)

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Some rural areas don't have sufficient wireless data coverage for farm equipment to remain to online full time.



Remote Sensors

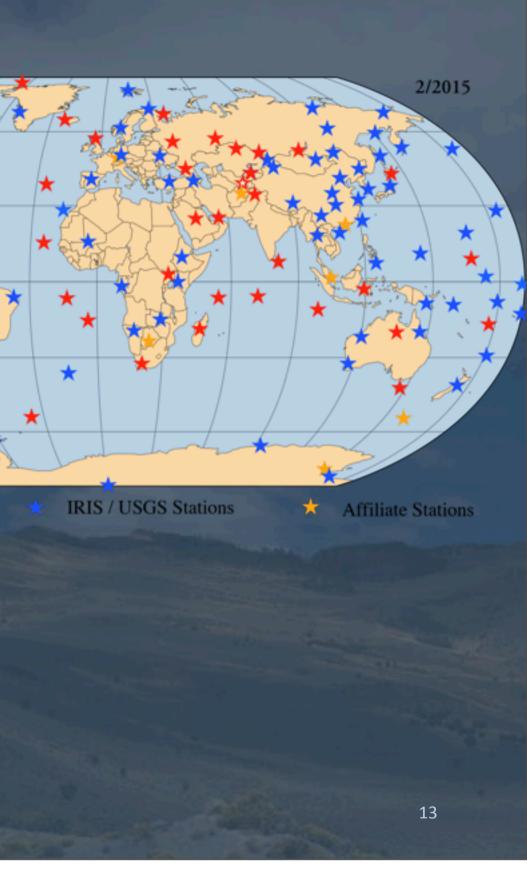
Human to Real-time Responsiveness: Earthquake, nuclear test sensor networks. Climate change monitoring

IRIS / IDA Stations Planned Stations

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For earthquake sensor networks, you want to get the information to emergency services and community alarm systems in milliseconds.

photo: http://www.iris.edu/hq/programs/gsn



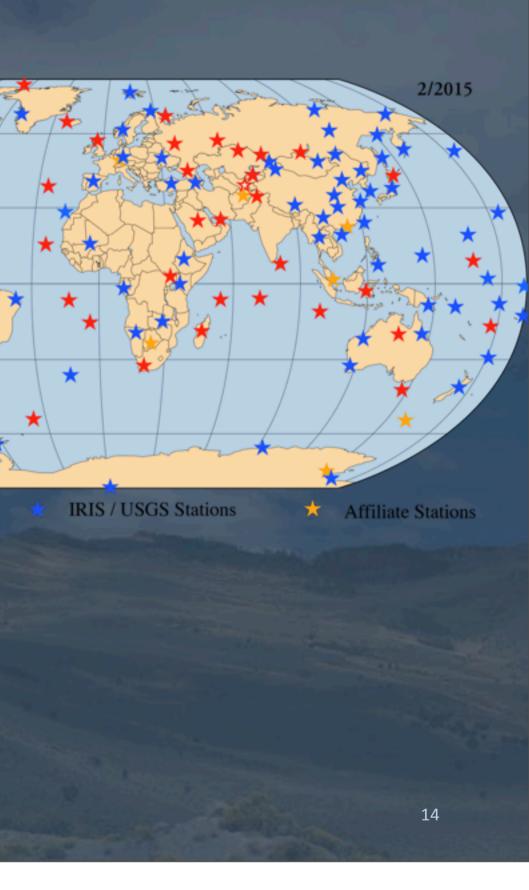
Remote Sensors

Characteristics: Redundant sensors Low-latency connections Low-bandwidth requirements

IRIS / IDA Stations Planned Stations

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This requires redundant sensors, always on connectivity, and low-latency connections. The amount of data isn't large. Some networks, like monitoring rainfall or glaciers for climate change studies, might be offline except for once-peryear downloads done onsite!



Robotics

Connectivity:
Two-way, but time of flight matters!
Autonomous?

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Some rural areas don't have sufficient wireless data coverage for farm robots to remain to online full time. The oneway time of flight between Earth and Mars is ~8 minutes. Quadcopter photo: <u>http://www.dji.com/product/phantom</u> Mars rover photo: <u>http://en.wikipedia.org/wiki/Mars_Exploration_Rover</u>

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Health Monitoring

Characteristics: Occasional to always-on connectivity • Detect health emergencies: call for help?

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Health monitoring tools are most popular for gathering activity data and some vital signs for analysis later. Some monitors are designed to detect medical emergencies and call for help when needed. photo: http://www.fitbit.com/force



Home Automation

Characteristics: • ToD packet storms • Fire & break-in detection: automatic notification of authorities

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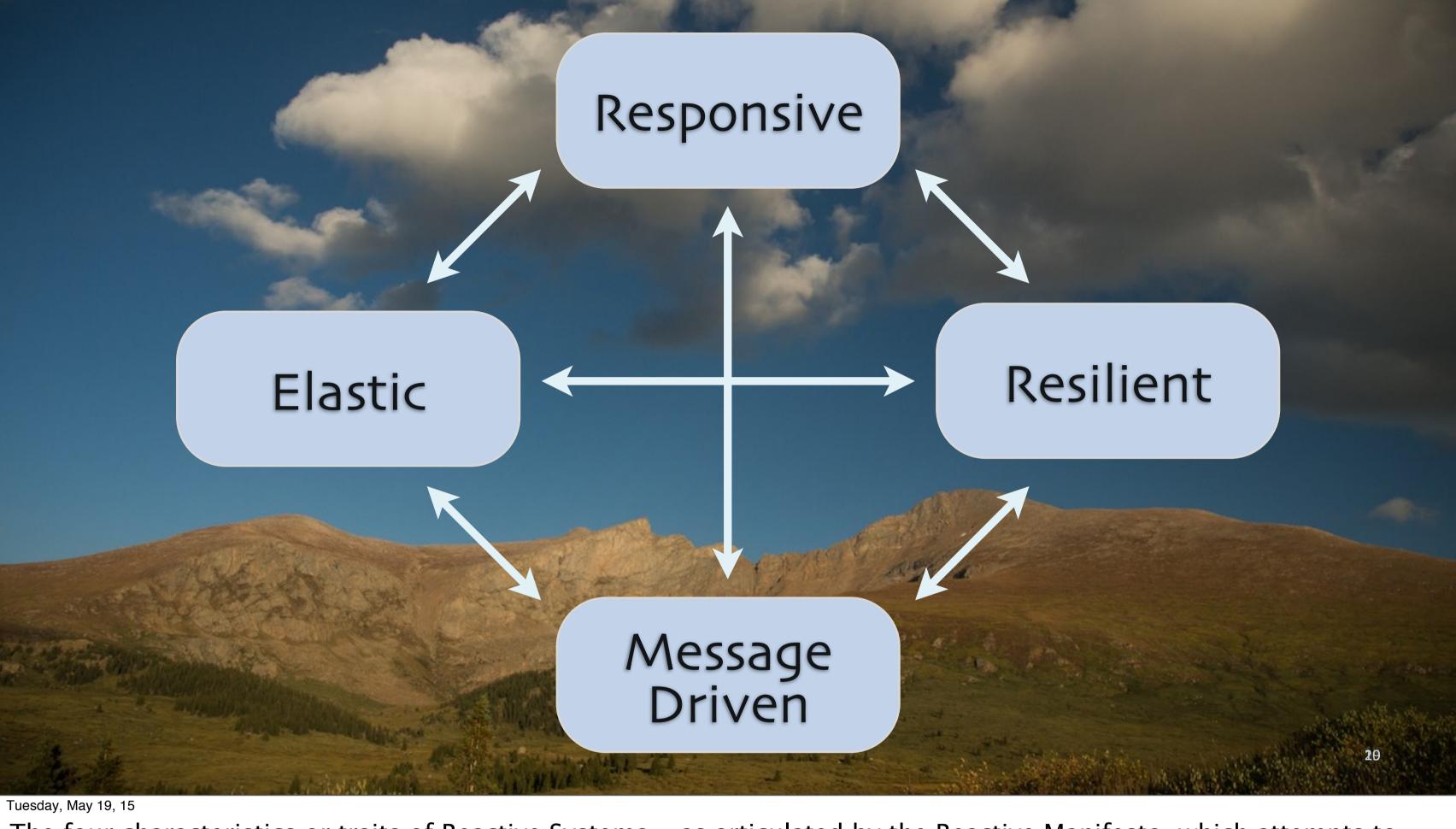
These systems are subject to time of day packet storms, e.g., while everyone in a given time zone is waking up or going to bed.

photo: https://store.nest.com/product/thermostat/





The idea of Reactive Systems emerged to catalog several common characteristics of the systems we have to build to support these scenarios, without over-specifying how these characteristics are satisfied.



The four characteristics or traits of Reactive Systems... as articulated by the Reactive Manifesto, which attempts to codify lessons learned across many projects, industries, and years building highly available, scalable, and reliable systems.

www.reactivemanifesto.org

The Reactive Manifesto

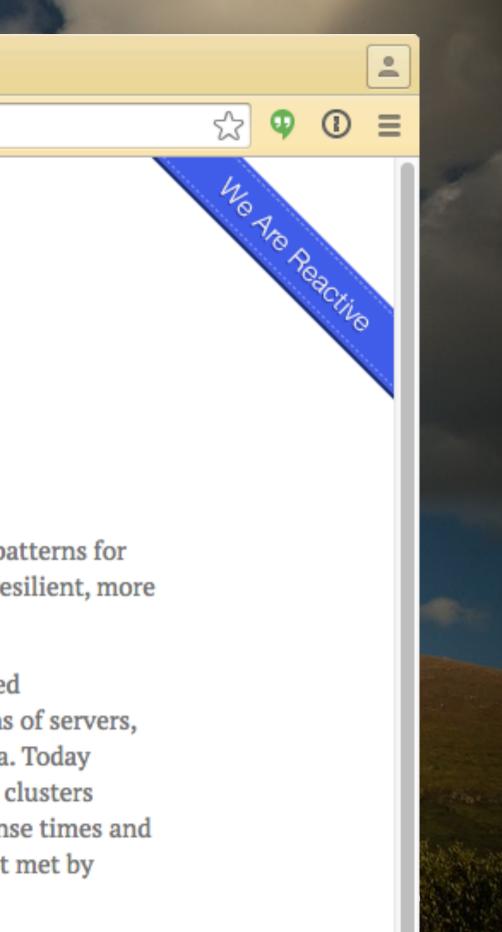
Published on September 16 2014. (v2.0)

Organisations working in disparate domains are independently discovering patterns for building software that look the same. These systems are more robust, more resilient, more flexible and better positioned to meet modern demands.

These changes are happening because application requirements have changed dramatically in recent years. Only a few years ago a large application had tens of servers, seconds of response time, hours of offline maintenance and gigabytes of data. Today applications are deployed on everything from mobile devices to cloud-based clusters running thousands of multi-core processors. Users expect millisecond response times and 100% uptime. Data is measured in Petabytes. Today's demands are simply not met by yesterday's software architectures.

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The four characteristics of Reactive Systems... as articulated by the Reactive Manifesto, which attempts to codify lessons learned across many projects, industries, and years building highly available, scalable, and reliable systems.





Tuesday, May 19, 15 Before discussing them in detail, let's slay some myths.

"This is new."

Mythese

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The RM attempts to codify lessons learned over many years in many scenarios. It's not new. It doesn't claim to be new.



Month of the second sec

"This is Typesafe marketing."

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While Typesafe's Jonas Bonér was one of the originators of the RM, other originators and contributions include experts in many companies and specialties.



Industry Adoption

https://spring.io/blog/2013/05/13/reactor-a-foundation-for-asynchronous-applications-on-the-jvm



ENGINEERING

Reactor - a foundation for asynchronous applications on the JVM



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A few industry heavyweights that are embracing Reactive. First, Spring's Reactor



DOCS

GUIDES

PRC

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Oracle Java 8 ME Embedded + Raspberry Pi + Sensors = IoT World

By Yolande Poirier-Oracle on May 13, 2015

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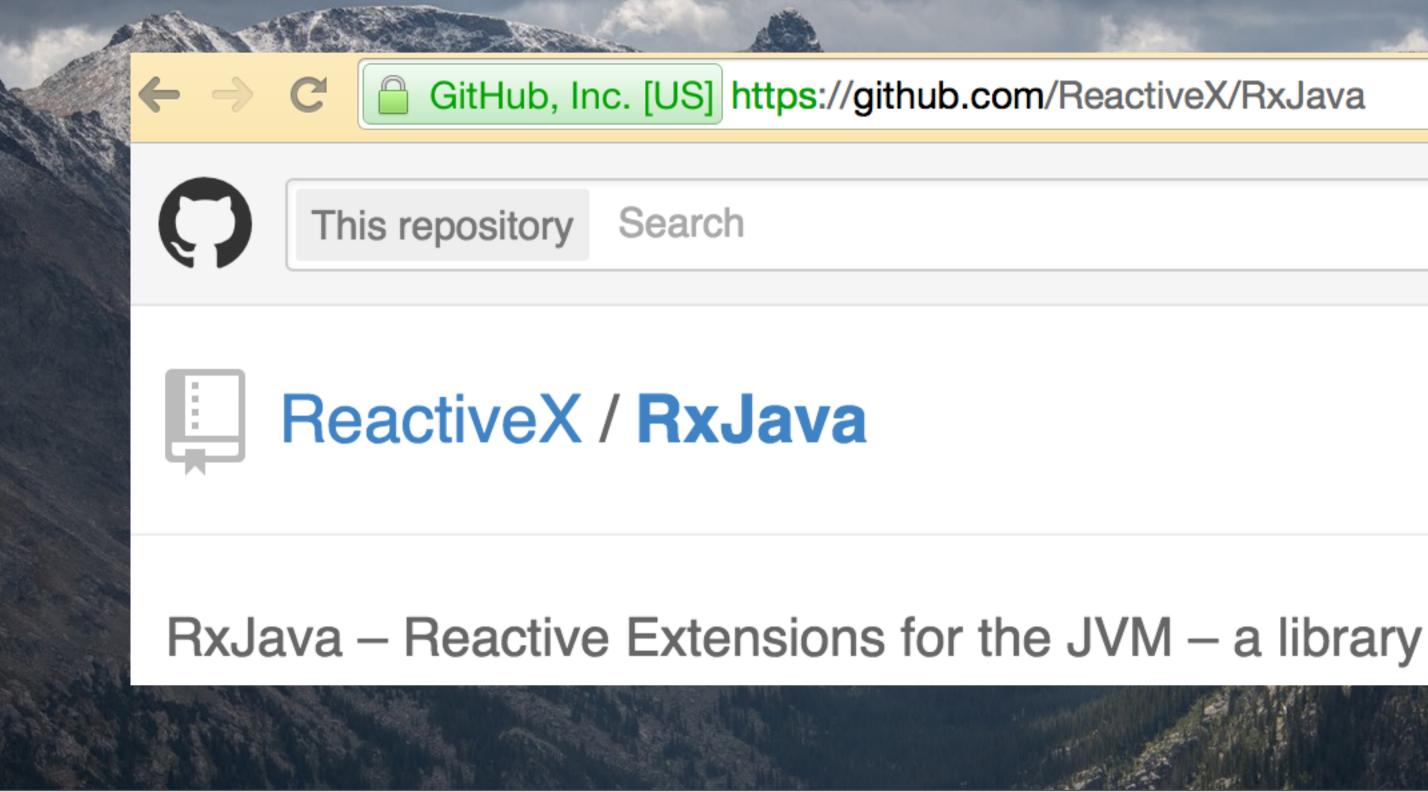
Even Oracle is embracing Reactive principles for Java EE.

ADS SUPPORT

« Java 9 Schedule | Ma

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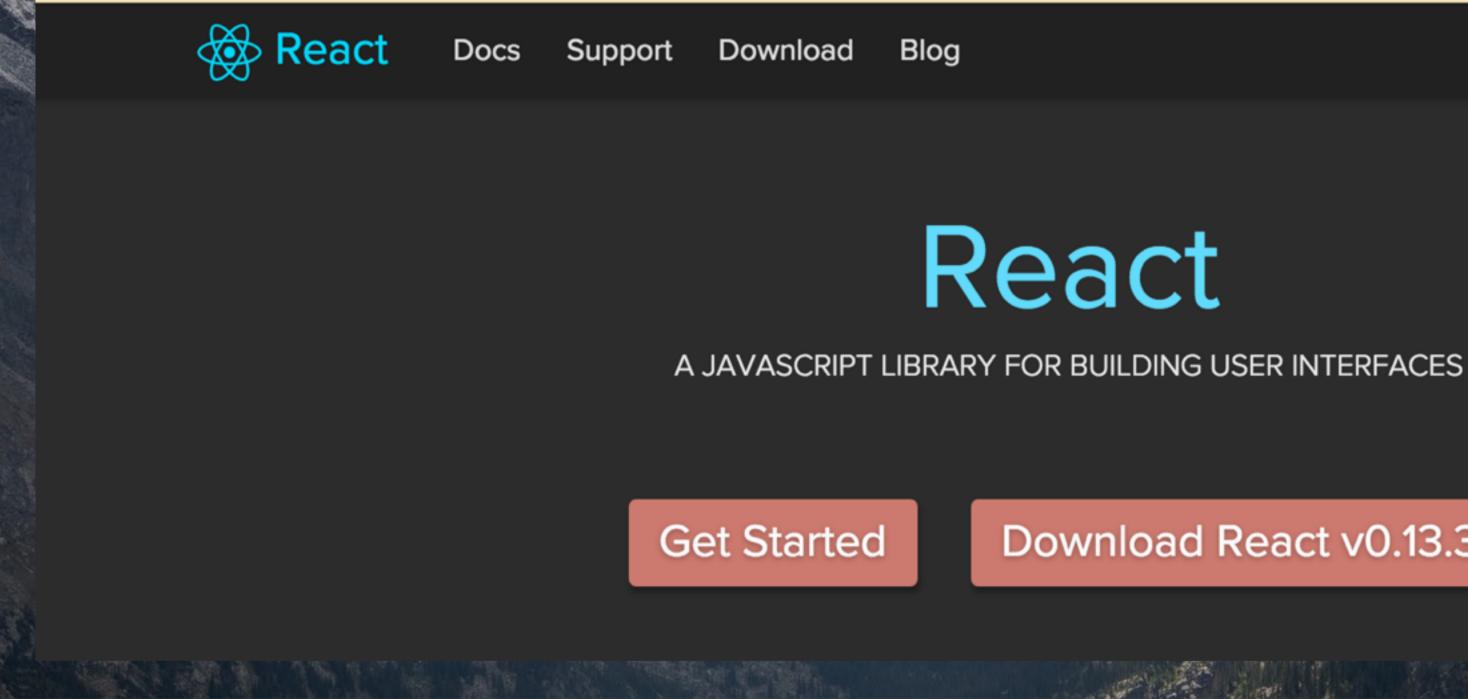


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Netflix created RxJava. (We'll define "Reactive Extensions")

Industry Adoption

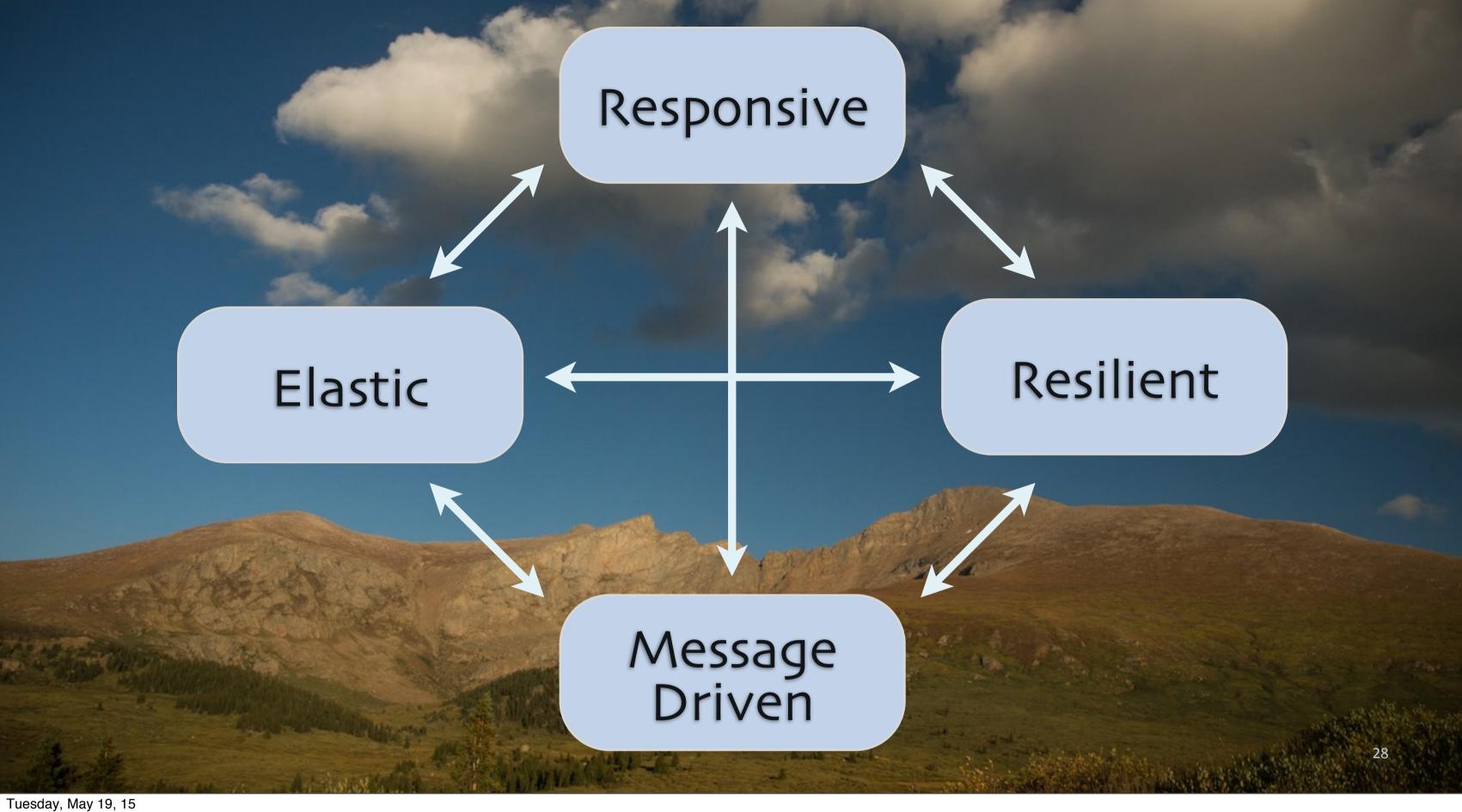
https://facebook.github.io/react/



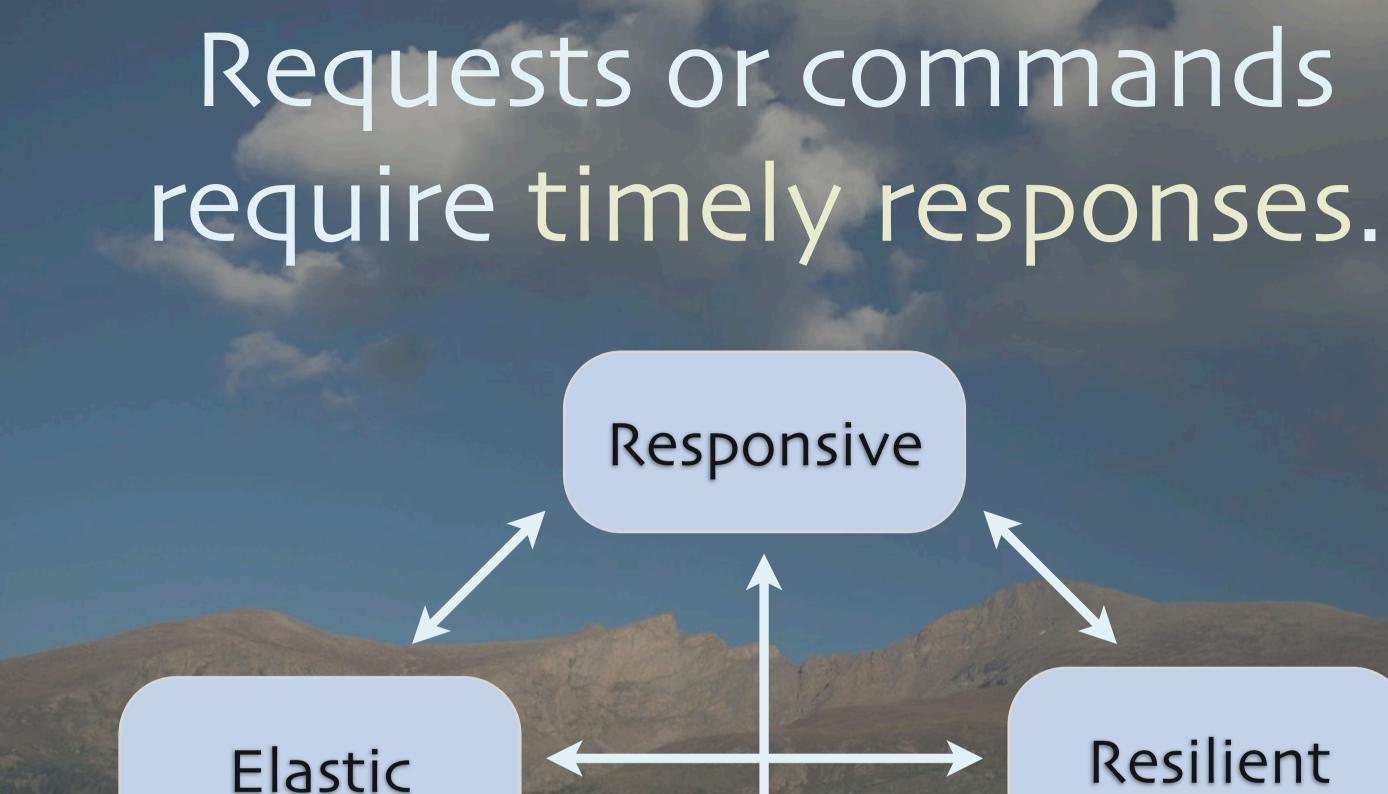
Tuesday, May 19, 15 Facebook's JS framework.



Download React v0.13.3



Now let's explore the four traits of Reactive systems.



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What does it mean if a service you rely on fails to respond to requests for service?

Resilient

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Cornerstone of usability and utility.

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Requires rapid detection of errors and quick responses.

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Requires predictable response times and quality of service.

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Requires pre-planned graceful degradation of service.

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You should plan in advance what level of service you'll provide if (or better, when) certain failure scenarios arise.



Awareness of time is first class.

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You have to be a clock watcher of sorts.



Example:



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For each trait, I'll cite some good examples of adding the trait. Image from <u>http://devops.com/features/netflix-the-</u> simian-army-and-the-culture-of-freedom-and-responsibility/

Clobber services, servers, even data centers in production, to verify service continuity.

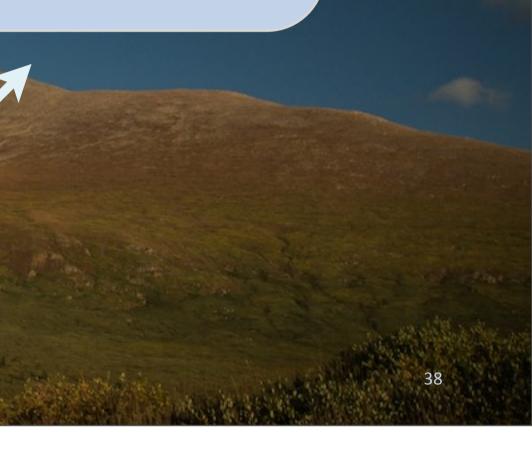
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Message Driven







Truly resilient systems must treat failures as routine, in some sense of the word, because they are inevitable when the systems are big enough and run long enough.

Recovers from errors

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Failure is not disruptive.



Failure is expected.



So, failure must be first class.

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A normal part of your domain model, implementation, etc.



Requires replication, containment, isolation, and delegation.

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Replication – other copies (data and services) replaced lost copies. Containment and isolation – firewalls stop disaster from spreading. Delegation – indirection to allow new copies to step into "holes".



Requires separation between normal control flow and error handling.

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We'll see an example of what I mean.



Example: Failure-handling in Actor Systems

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The Netflix Simian Army could also be cited here.

We'll come back and fill in details of Actor systems shortly. For now, let's focus on error handling.



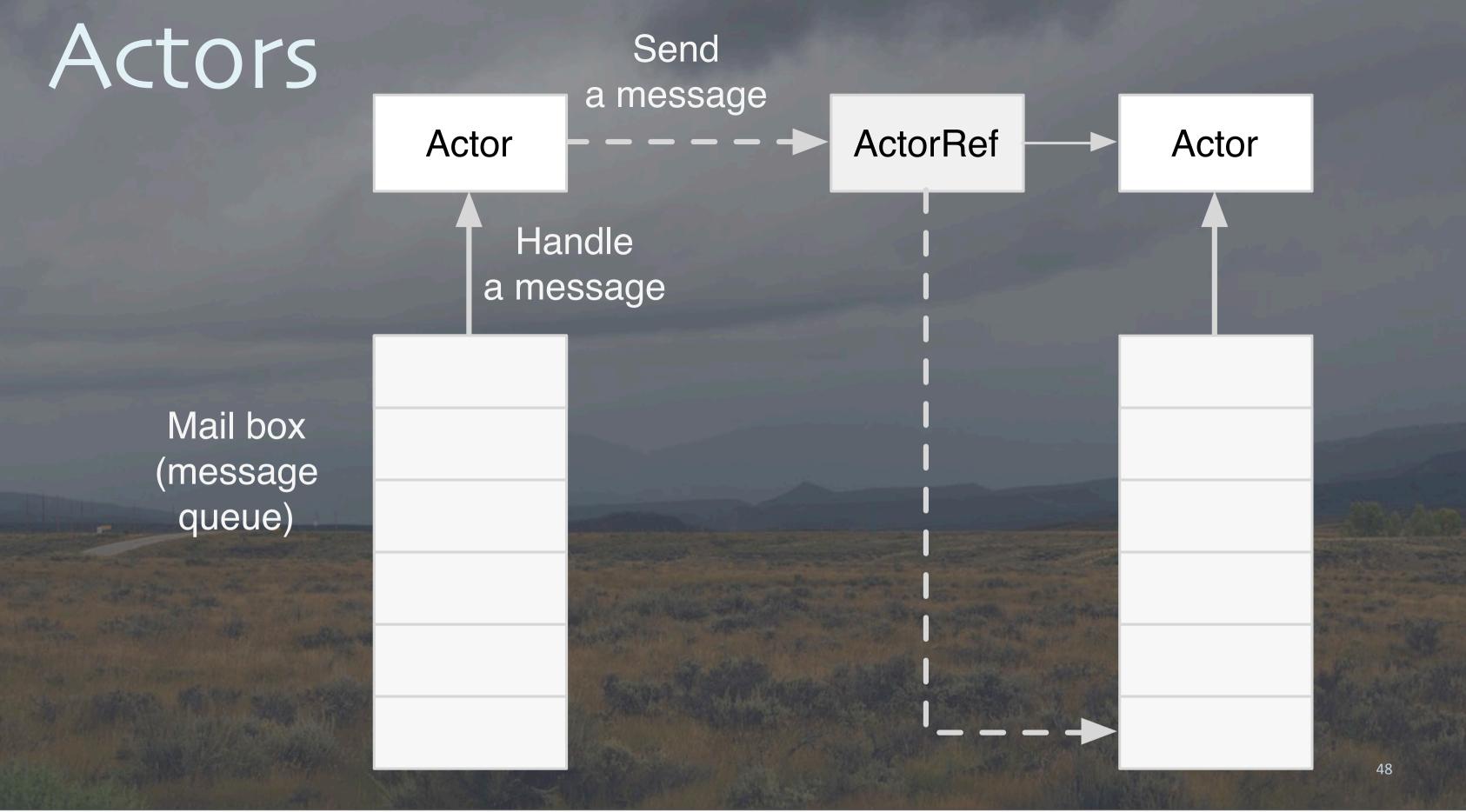
Let it Crash!



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Rather than attempt to recover from errors inside the domain logic (e.g., elaborate exception handling), allow services to fail, but with failure detection and reconstruction of those services, plus failover to other replicas.





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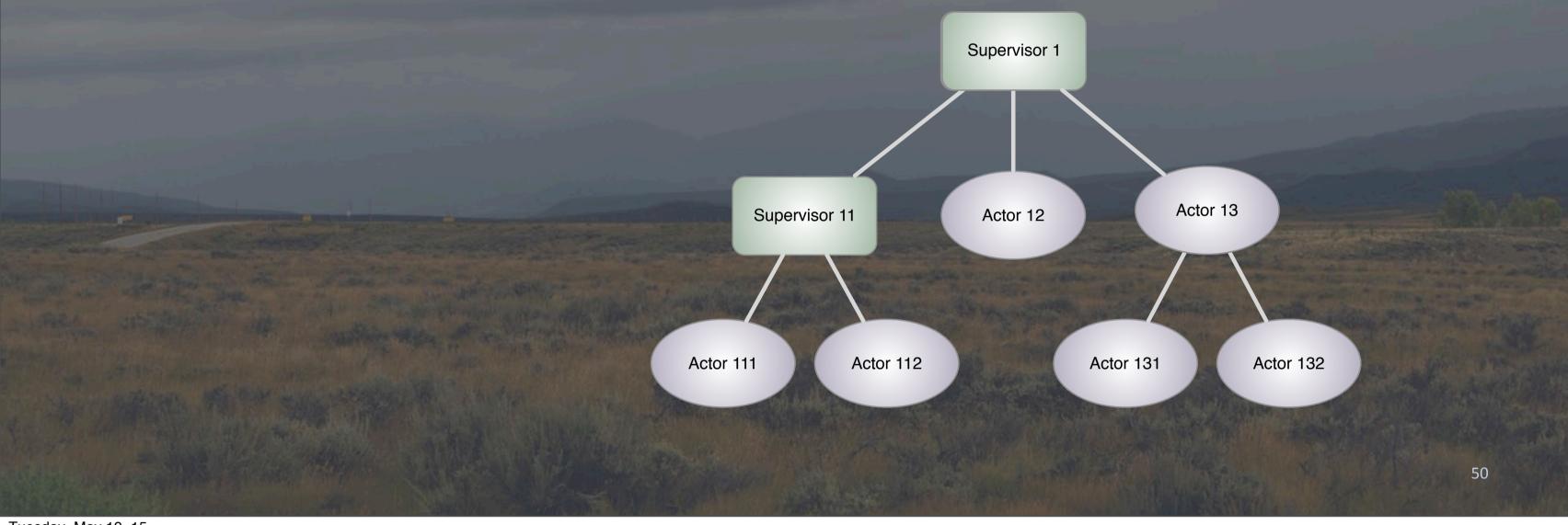
Actors are similar to objects in Smalltalk and similar, message-passing systems; autonomous agents with defined boundaries that communicate through message passing. Actors, though process each message in a threadsafe way, so they are great for concurrency. (This diagram illustrates the Akka implementation – <u>http://akka.io</u>)



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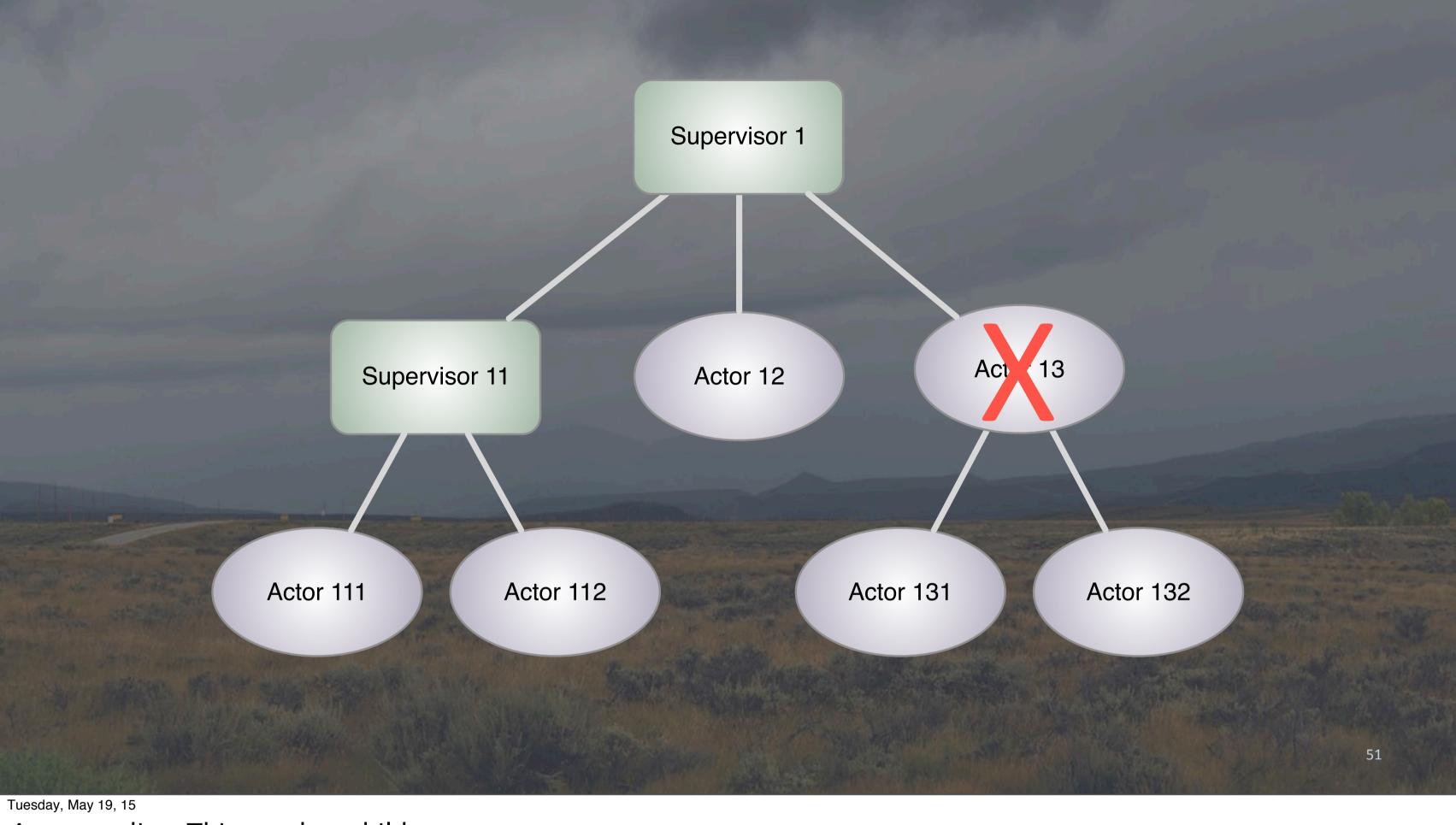
There are lots of so-called Actor systems, but be wary of them unless they have this sophisticated supervision model or something like it (even though the original Actor model of Hewitt, et al., didn't include supervision like this...).

Generalizes nicely to distributed actor systems.

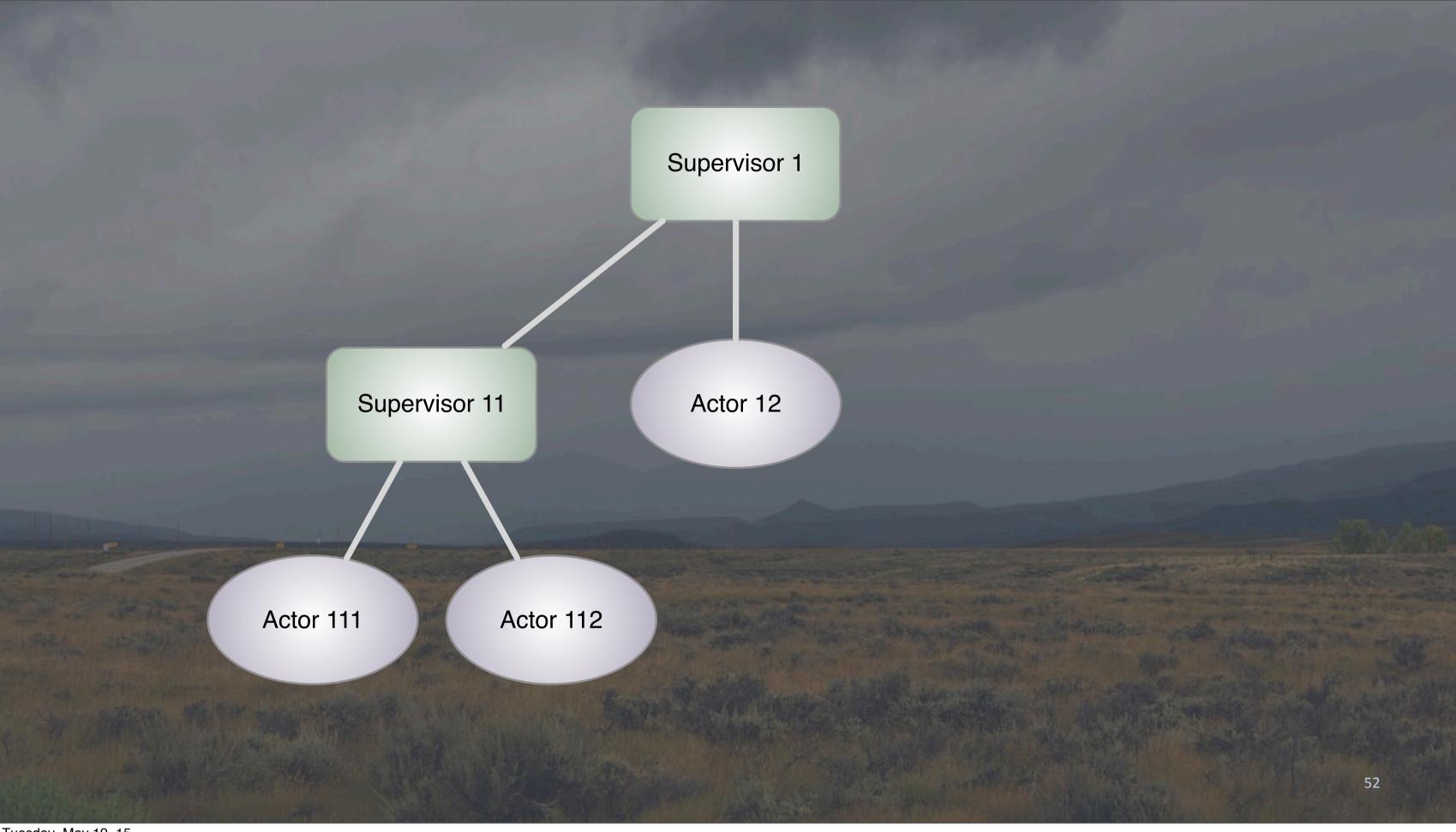


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Uniform abstraction when the lines cross process and machine boundaries.

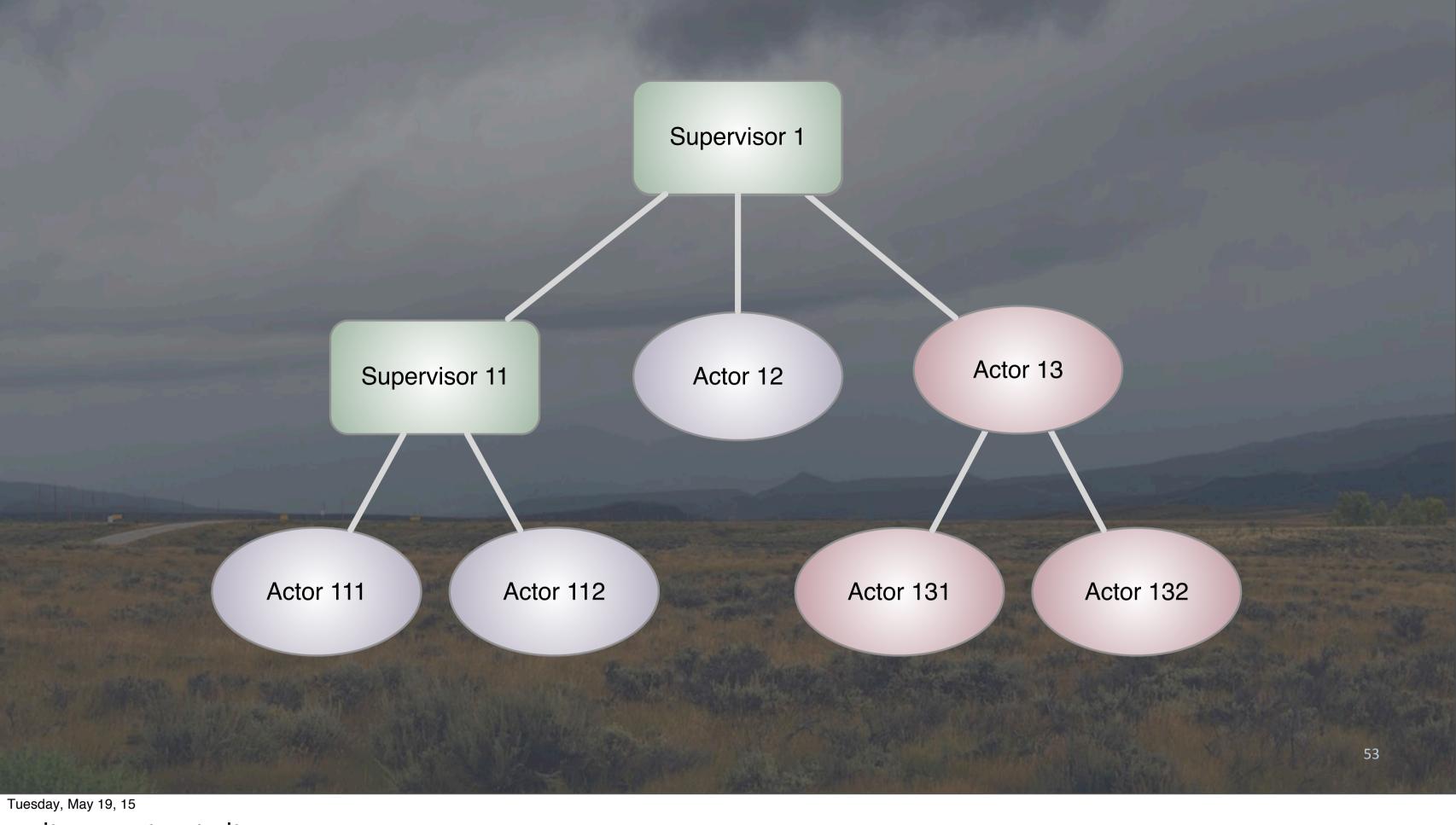


An actor dies. This one has children, too.



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The supervisor tears down the tree of dependent actors, then...



... it reconstructs it.

Clean separation of normal processing from recovery.

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Very important at scale. Exception handling is too limited for large-scale recovery and mixing error handling with normal logic complicates code.



Not using Actors? Consider Hystrix from Netflix or similar...

https://github.com/Netflix/Hystrix

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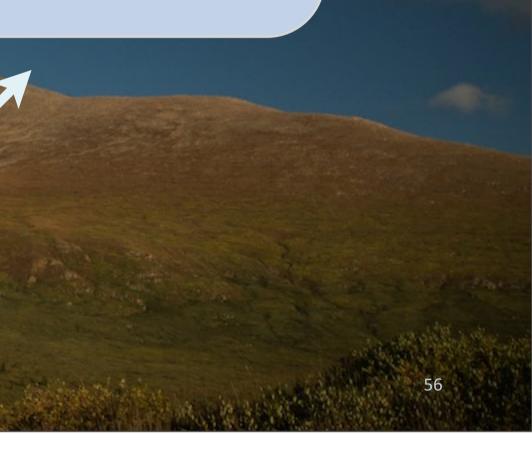
I believe every environment must solve this problem one way or another.

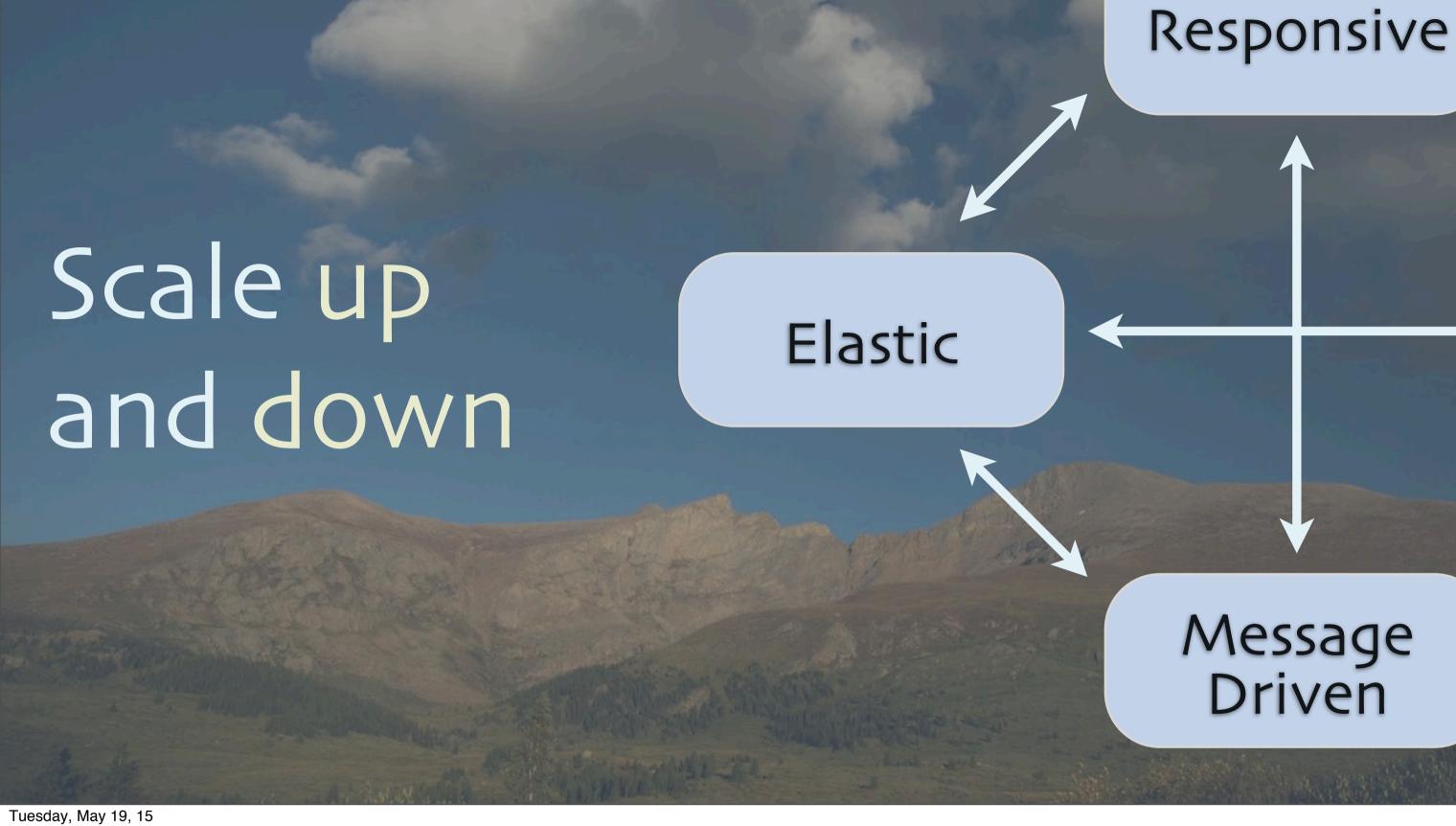
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Message Driven







As demand rises and falls, you must gracefully scale up to meet increasing demand and scale down to conserve resources.

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Detect changing input patterns.

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Not as trivial as it might sound. Just how big is this spike going to be? When do I pull the trigger to grow or shrink resources? Machine learning is sometimes used to predict when to change based on past experience.



Automatically adjust services.

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Human intervention has to be minimal for this to really work.



Scale across commodity hardware.

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Typically you use redundant services again, across commodity (interchangeable) hardware.

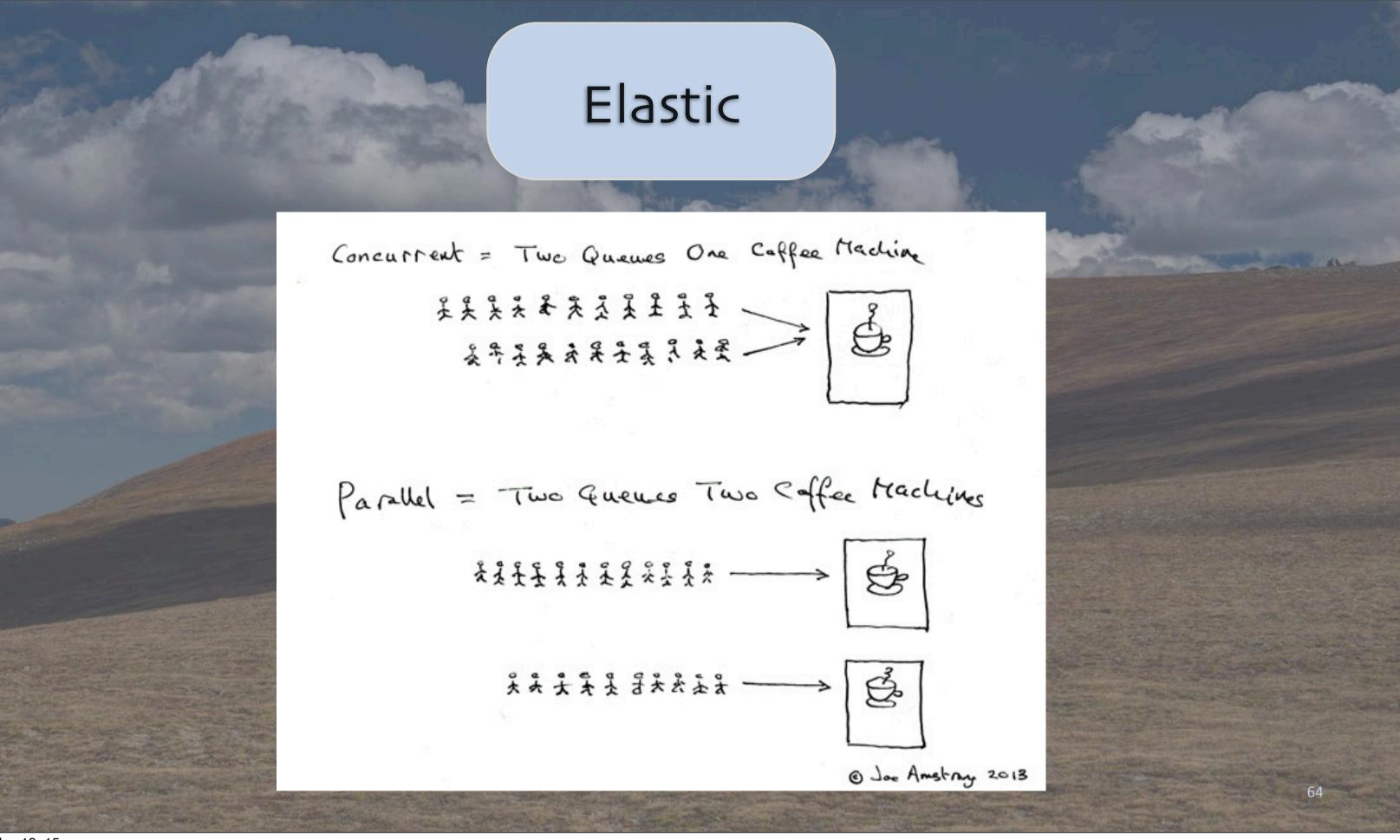


No bottlenecks or contention points.



To scale down, must be able to drain services from nodes.

Tuesday, May 19, 15 So, harder if the nodes hold data!

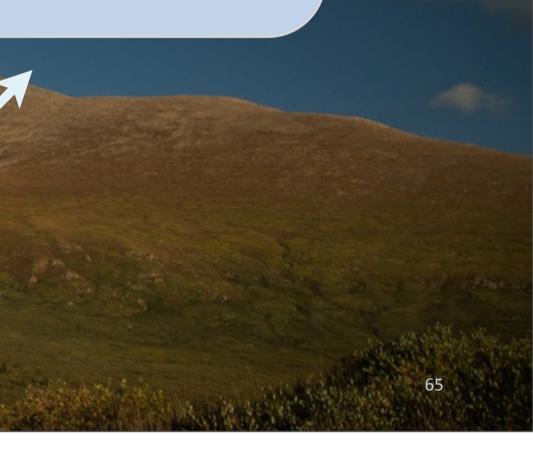


Tuesday, May 19, 15 "Concurrent" vs. "parallel".



Message Driven







To react, you must be message driven.

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To be responsive to the world around you, you must interact with it through messages.

Resilient







Asynchronous message passing.

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It can't be command and control. Blocking while waiting for a response fails to scale. (See Amdahl's Law)



Defines boundaries, promotes loose coupling and isolation.

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Clear separation between components (whether or not the messages cross process boundaries), which encourages effective decomposition into focused services that are isolated from each other and loosely coupled.



Promotes location transparency.

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Source and receiver can change, so services can be migrated to adapt to changing load dynamics.



Handle errors as messages.

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Also, you can use the same message infrastructure to communicate error scenarios as well as normal processing.



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Promotes global management and flow control through back pressure.

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Think of the messages as forming a stream. If a common implementation infrastructure is used, it's possible to monitor and manage traffic flow. Back pressure is the idea of communication between sender and receiver to control the rate of flow. We'll return to it.

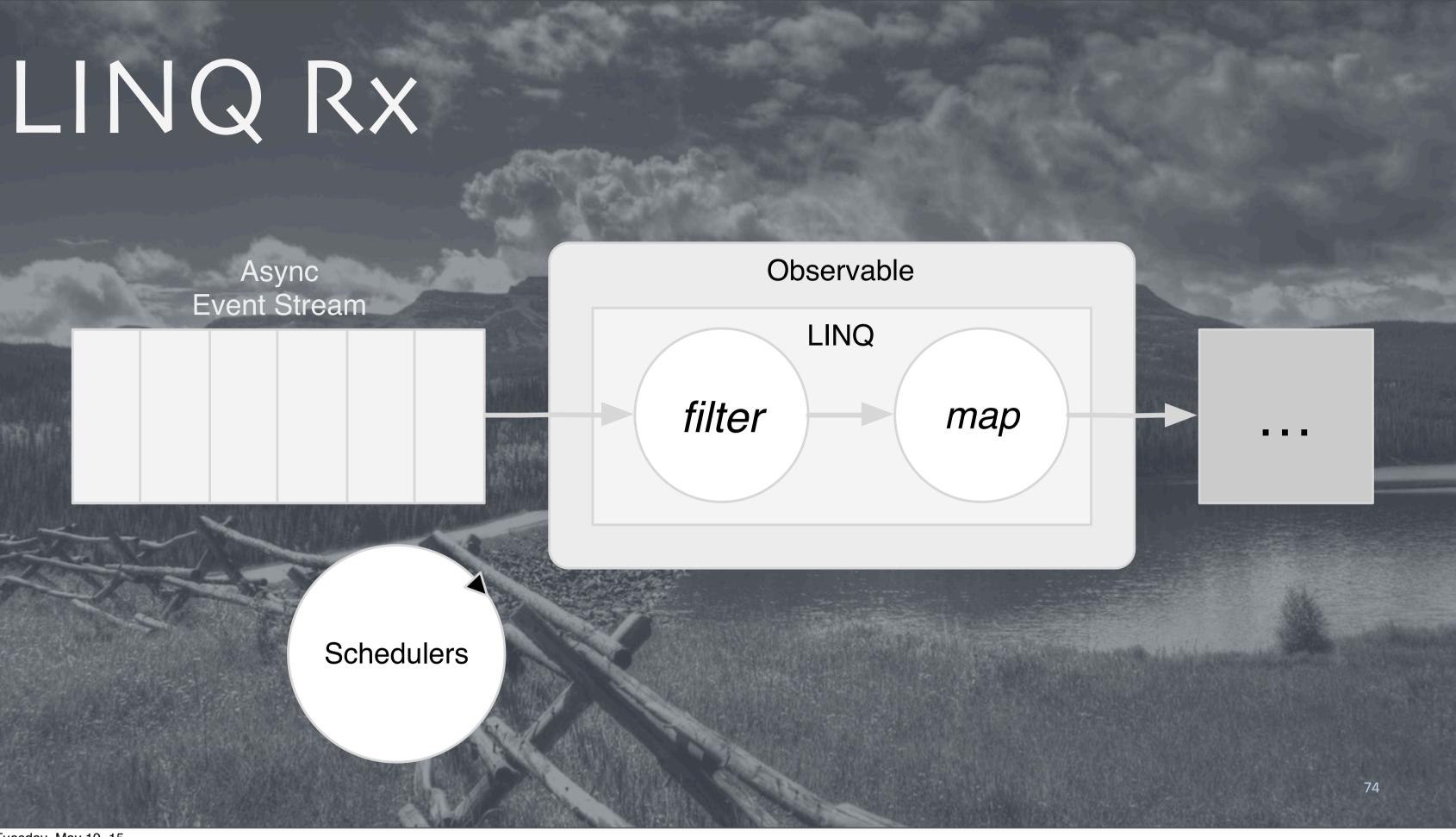


Reactive Extensions (Rx)

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Rx was pioneered by Erik Meijer for .NET. Now ported to several languages, including RxJava (Netflix) and React (JS – Facebook).





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Events are observed (an extension of the observer pattern). Operations like filtering and mapping are provided to work with the stream through LINQ (Language Integrated Query), which uses SQL-like expressions. The Schedulers are used to trigger processing.

Events pushed to system.

Tuesday, May 19, 15 It's essentially a push model.



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FP/SQL-like query semantics to manipulate events.

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How: Reactive Tools



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We mentioned a few already, let's fill in some details. This won't be an exhaustive list. Hat tip to Jamie Allen at Typesafe for some of these ideas.



How: Reactive Tools

 Functional Programming Distributed Computing "Laws" Software Transactional Mem. • Event Loops

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We mentioned a few already, let's fill in some details. This won't be an exhaustive list.

How: Reactive Tools

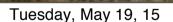
• CSP • Futures Actors - Erlang or Akka Rx and variants Reactive Streams

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CSP – Communicating Sequential Processes.









Prefer immutable values and side-effect free functions...

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... because they eliminate the problems of multithreading.

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Why, because all the problems are caused by attempting to coordinate access to shared, mutable state. If the state is no longer mutable, then it's trivial to share. There are many other advantages of FP.

hate the bading. 12

Objects - suitable for modules. Functions - for everything else.

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This is Scala's view, that objects are useful as module constructs, but the code inside should be functional.

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Architecture Side Note:

The biggest mistake of OOP was the idea that we should faithfully model the world in code.

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Controversial, but I believe much of our code bloat and inflexibility is actually caused by this mistaken belief. Example: Does a payroll calculator need the concepts of Pay, Deductions, etc.? Or should we just stream numbers through math logic?

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Distributed Computing





Distributed Computing

Need to be asynchronous and nonblocking, avoid locks.

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Messaging passing should be asynchronous. Any expensive calculation should be executed async, too, so main threads are not blocked. There are many lock-free algorithms and datastructures now. Locks kill scalability and they are hard to program correctly.



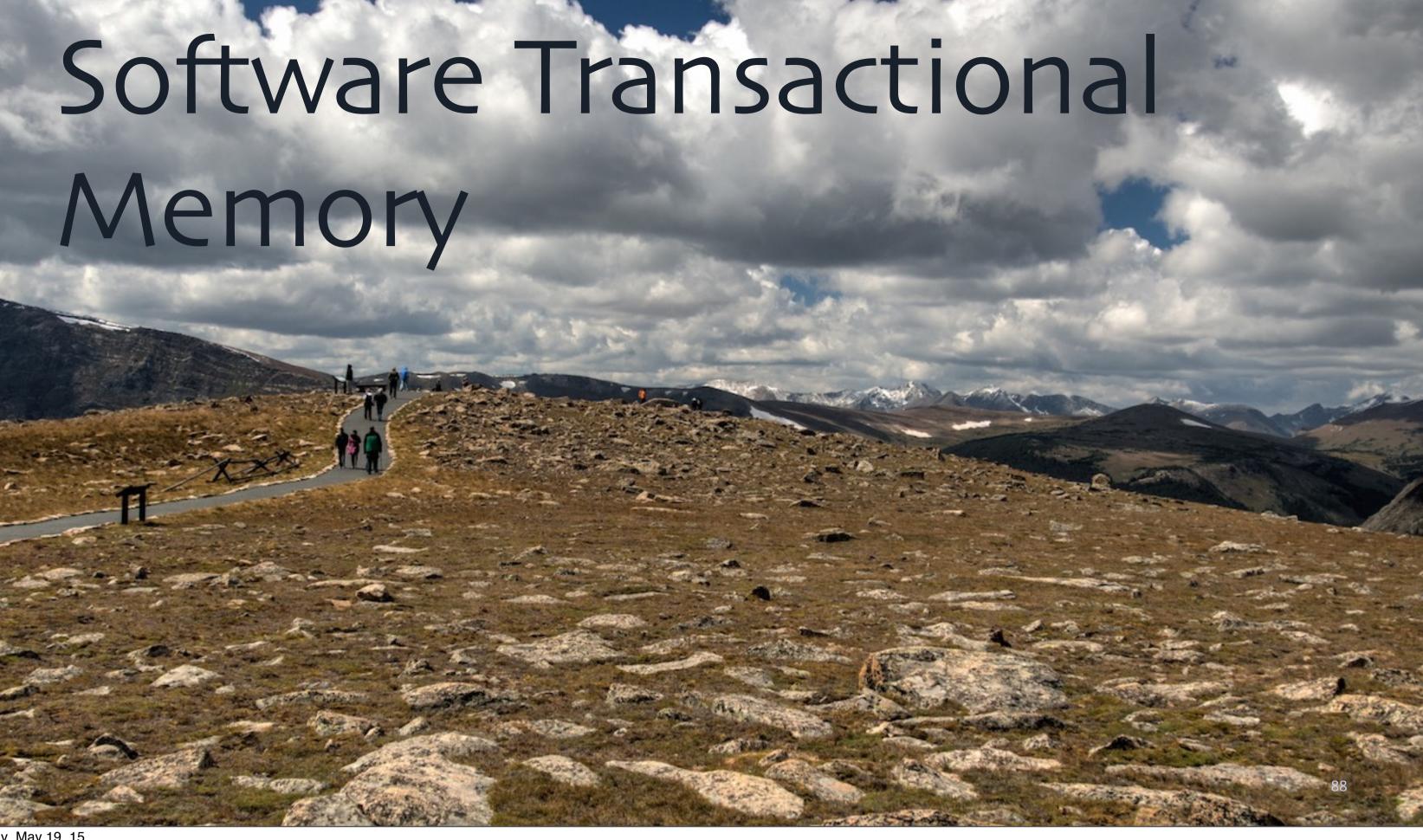


Distributed Computing

Serializability (order) and Linearizability (change history results in same order?). CRDTs, Lattices.

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CRDTs - Commutative Replicated Data Types (<u>http://pagesperso-systeme.lip6.fr/Marc.Shapiro/papers/RR-6956.pdf</u>) Lattices are more general concept applied here.



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Popularized first in Hardware, then in Software by Haskell. Now used in persistent datastructures in many languages. Great description of STM by Simon Peyton–Jones, from the O'Reilly Book Beautiful Code, <u>http://</u>research.microsoft.com/en-us/um/people/simonpj/papers/stm/#beautiful

Software Transactional Memory

Basically, ACID without the D.

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Software Transactional Memory

Principled local state mutation through transactions.

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Software Transactional Memory

Limited scalability, no distribution model.

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A very powerful tool for avoiding local locks and unprincipled mutation, but not a tool that scales to the global challenges we're discussing here.







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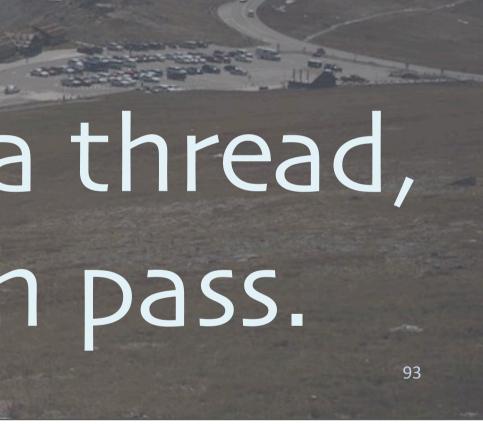
The standard technique for message/event driven programming. Usually pull based, for something that loops continuously pulling events off a queue, or push based with callbacks.

Event Loops

Loop continuously on a thread, pull an event on each pass.

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Consumes a thread, which can limit scalability. The event handler must not take too long or the queue can either grow to exhaust available memory (unbounded) or drop events (bounded).



Event Loops

Callbacks invoked when an event is pushed to it.

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Can use threads more efficiently, but callback hell is sometimes a problem.

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Event Loops

Needs a global strategy for error handling.

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Many of these systems don't provide facilities for distribution or error recovery.



CSP

Communicating Sequential Processes

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Communicating Sequential Processes – The first mathematical model of distributed computing. It has evolved somewhat and it's still popular in Clojure and Go, for example.

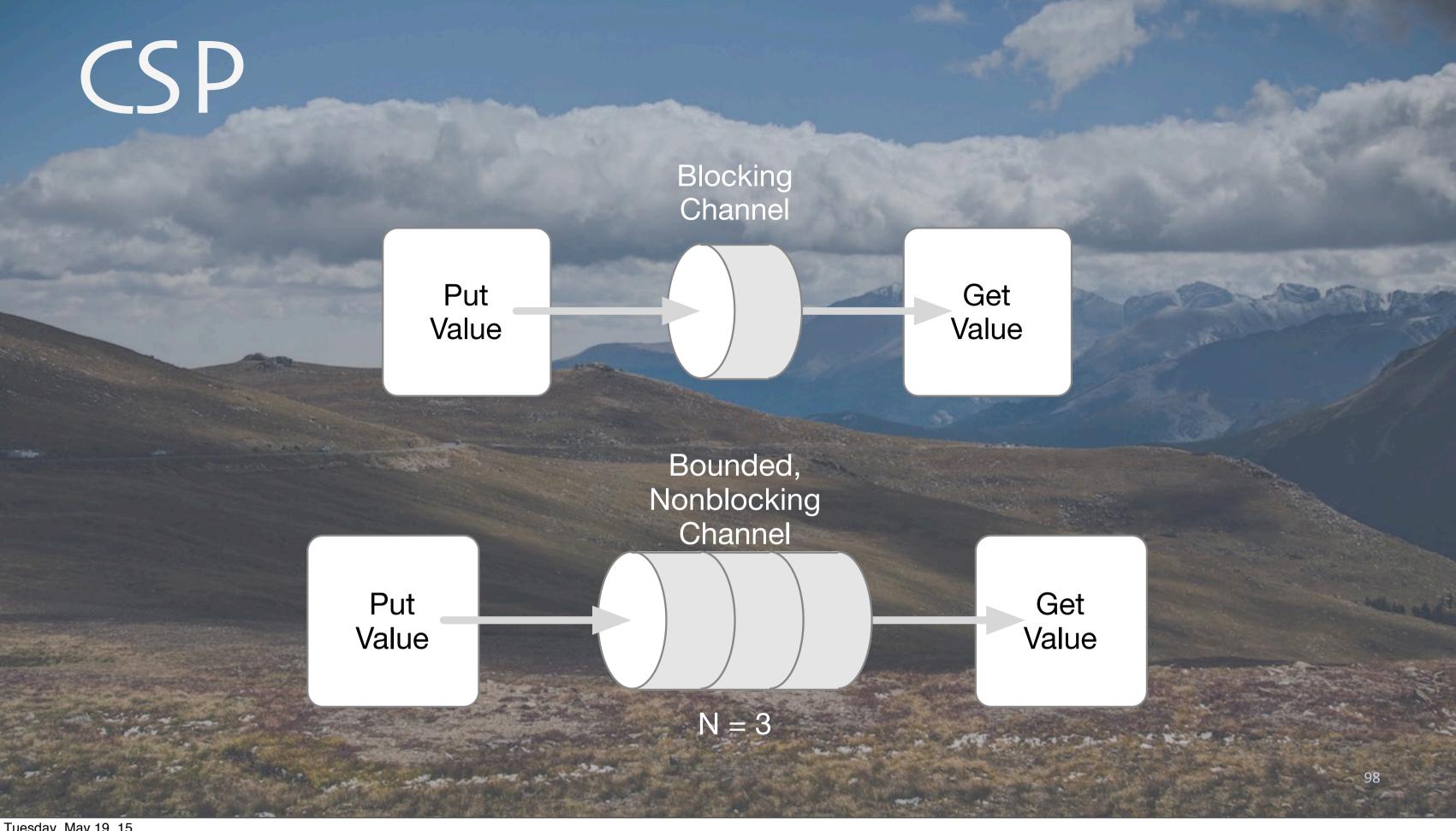


Decouple sender and receiver via a channel. Can be sync. or async. Not typically distributed...

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Great abstraction for coordinating exchange of data, with a level of abstraction, the channel. Not really a scalable distributed system in the general sense.





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Schematic view of simple CSP interactions. If the channel queue has one slot, then it's blocking; the "putter" wait for a "" "" "getter" to be on the other side. If there are >1 slots, the putter won't block unless all the slots are full. See my talk on error handling in reactive systems where I discuss CSP in more detail. (I'll discuss CSP vs. Actors in more depth in my other talk.)

Futures



Fill more or less the same niche as CSP. That is, most Futures and CSP systems cover the same scope of concurrency control, which is somewhat fine-grained as opposed to strategic.

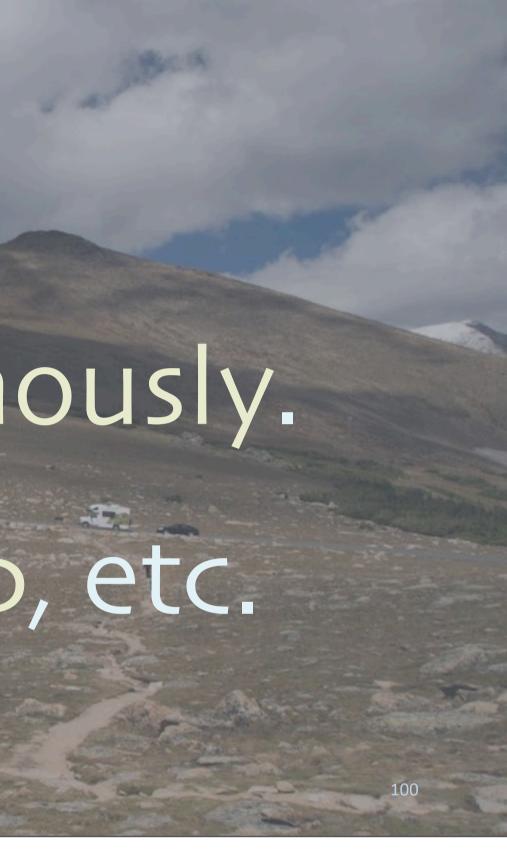


Futures

Run logic asynchronously. Apply map, flatMap, etc. to the results.

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Like using the UNIX shell to fire a process in the background, but you either define callbacks to handle the success or failure (a more procedure-oriented approach) or use functional operations like map, etc. to process the results on success.



Futures

Run logic asynchronously. Or use callbacks and error handlers.

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Like using the UNIX shell to fire a process in the background, but you either define callbacks to handle the success or failure (a more procedure-oriented approach) or use functional operations like map, etc. to process the results on success.



Actor Systems

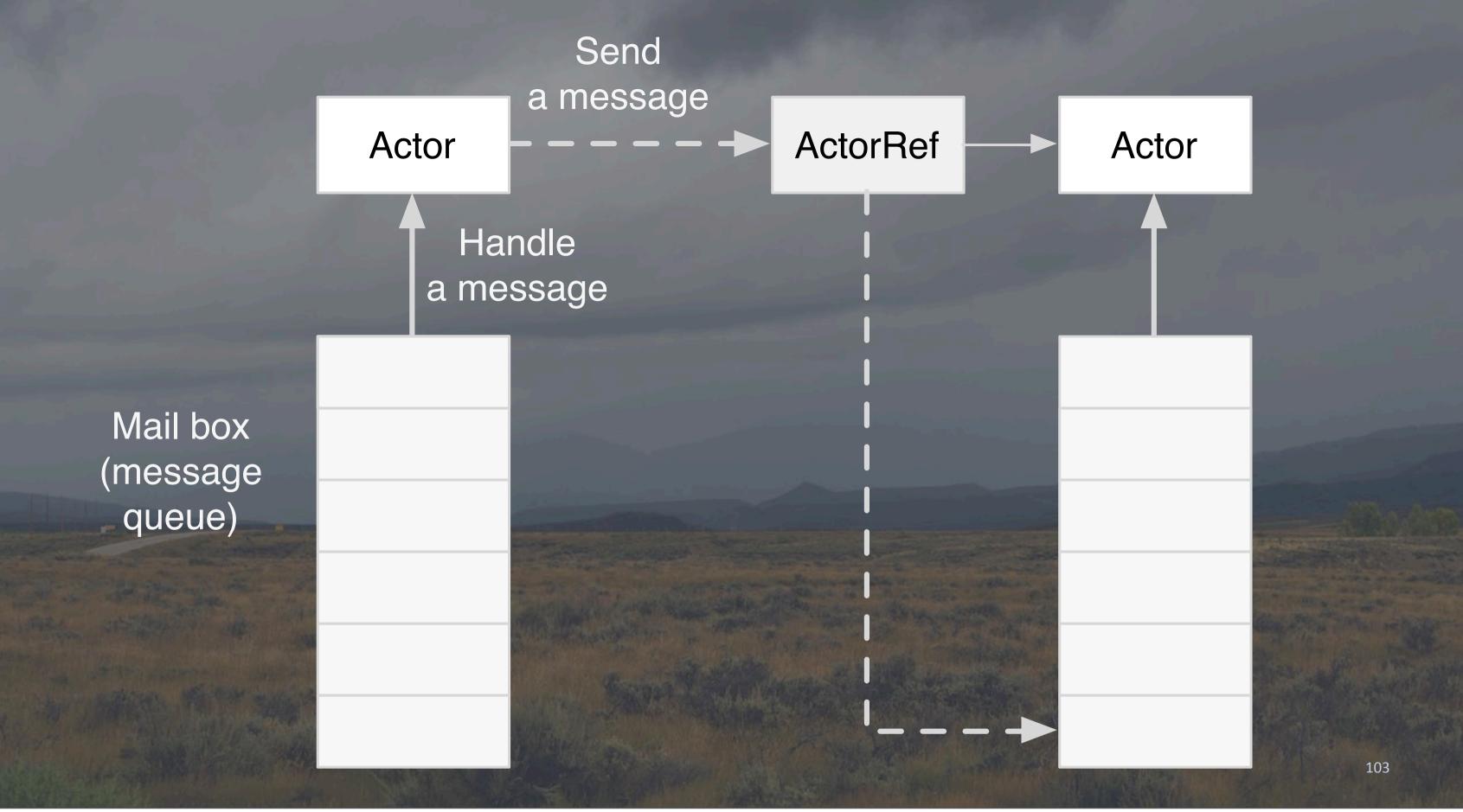
Let it Crash!

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We briefly visited this before.

Rather than attempt to recover from errors inside the domain logic (e.g., elaborate exception handling), allow services to fail, but with failure detection and reconstruction of those services, plus failover to other replicas.





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Actors are similar to objects in Smalltalk and similar systems; autonomous agents with defined boundaries that communicate through message passing. Actors, though process each message in a threadsafe way, so they are great for concurrency. (This diagram illustrates the Akka implementation – <u>http://akka.io</u>)

Actor Systems

Pioneered by Hewitt, et al. 1973. Made popular by Erlang, which introduced Supervision.

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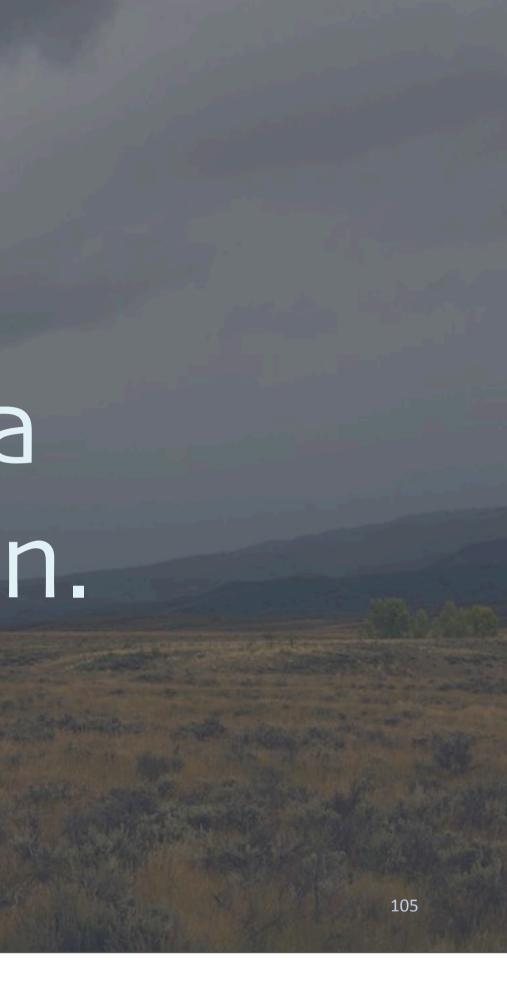
Erlang is a simple language with actor semantics baked in. It has been used to create extremely reliable telecom switches, databases (e.g., Riak), and other services (e.g., GitHub).

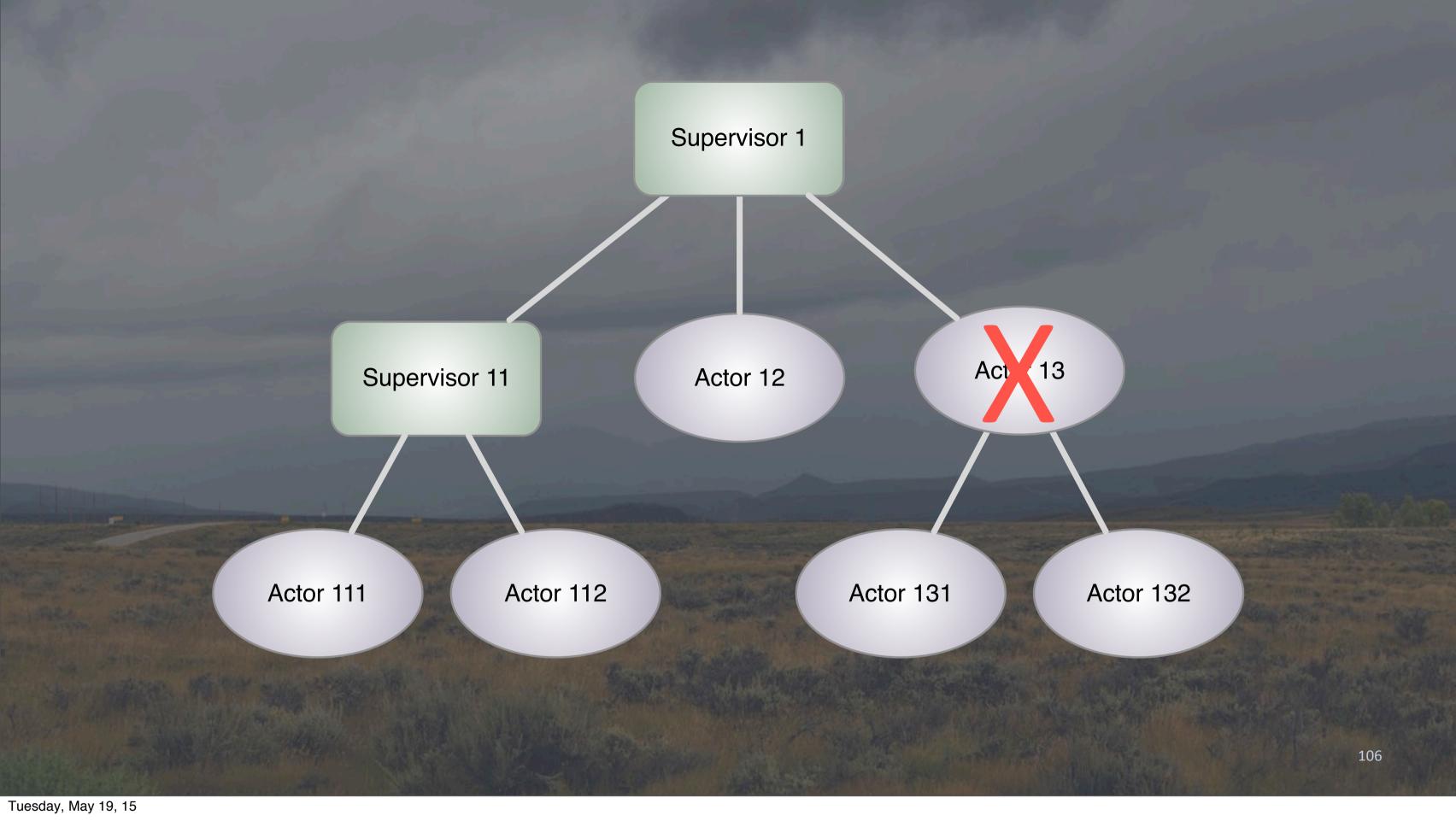
Actor Systems

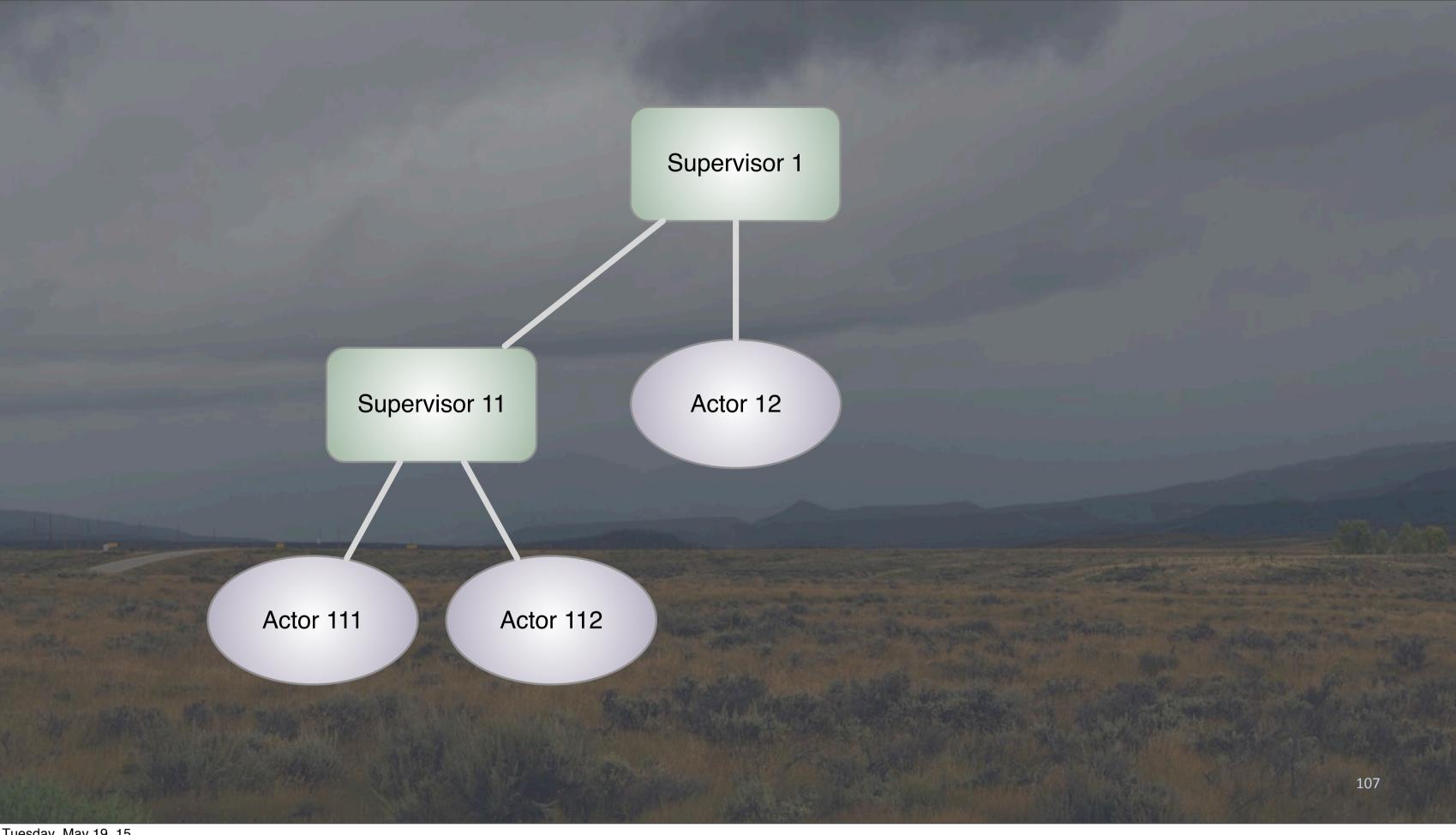
Distribution is a natural extension.

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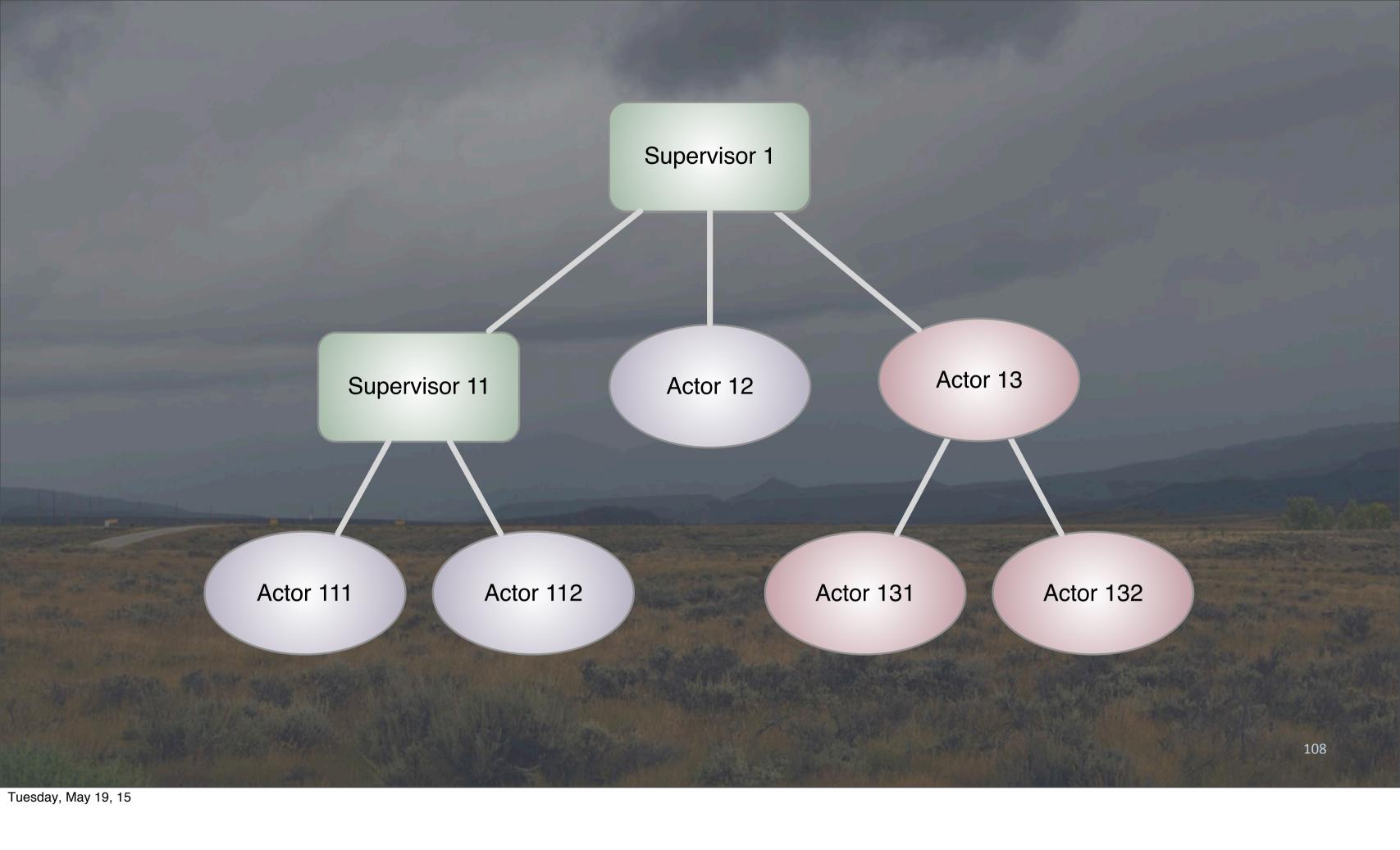
Erlang is a simple language with actor semantics baked in. It has been used to create extremely reliable telecom switches, databases (e.g., Riak), and other services (e.g., GitHub).







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The most sophisticated error recovery in reactive systems.

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Again, I'll discuss this in some more depth in my other talk.

Clean separation of normal processing from recovery.

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State mutation "firewalls". Supports location transparency.

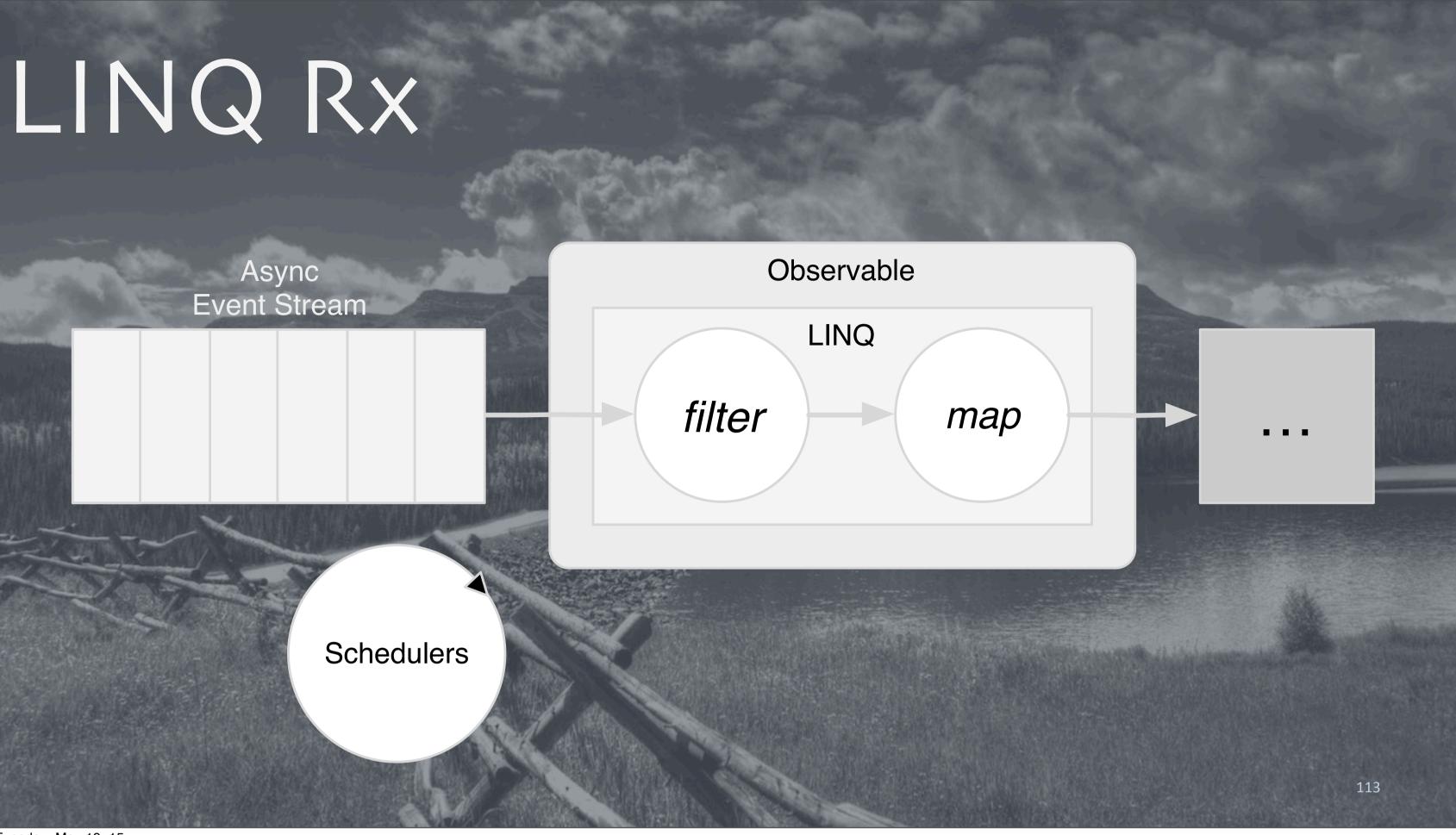
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Reactive Extensions (Rx)

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Pioneered by Erik Meijer for .NET. Now ported to several languages, including RxJava (Netflix) and React (JS -Facebook).





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Events are observed (an extension of the observer pattern). Operations like filtering and mapping are provided to work with the stream through LINQ (Language Integrated Query), which uses SQL-like expressions. The Schedulers are used to trigger processing.

Events pushed to system.

Tuesday, May 19, 15 It's essentially a push model.



FP/SQL-like query semantics to manipulate events.

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RX

Combines Iterator and Observer into Observable. Stream oriented.

Tuesday, May 19, 15 I didn't mention this before.



Rx

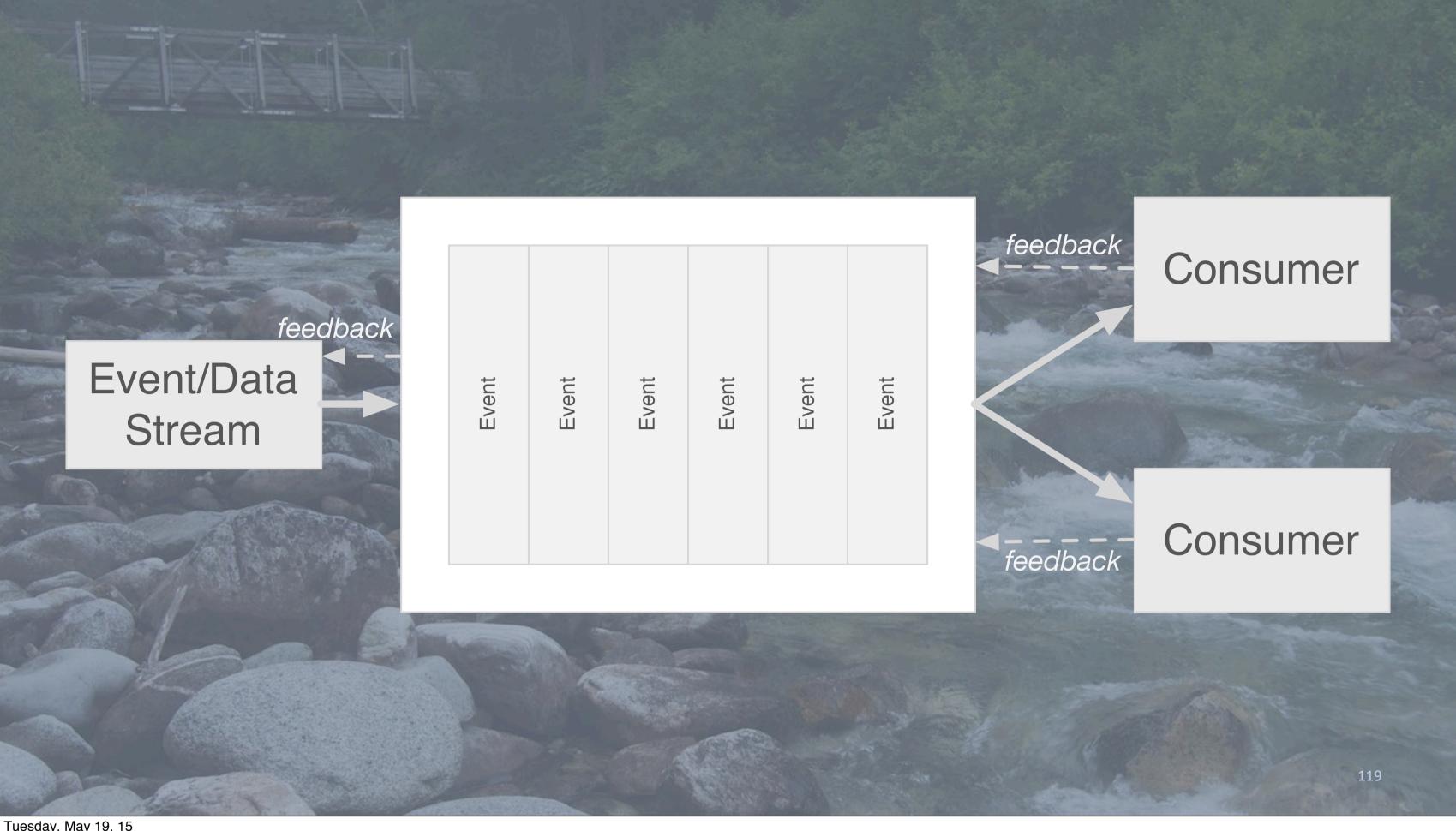
Need to add your own fault-tolerance model.

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reactive-streams.org

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A standard with many implementations for streaming systems with truly "reactive" behavior. photo: Bridge Creek, North Cascades National Park, Washington State (not Colorado ;)



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A stream of events from some upstream producer to one or more downstream consumers. Typically, queues are used for buffering, since for asynchrony the production and consumption can't be in lock step, that is synchronized! But what happens if the queue is unbounded? Or bounded? That's where the feedback comes in.

Unbounded queues eventually exhaust the heap.

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Any rare, low-probability event will eventually happen for a system that's big enough or runs long enough. Any unbounded queue will eventually grow to consume all memory.

Bounded queues cause blocking or arbitrary dropping of events.

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Bounded queues avoid heap exhaustion, but force arbitrary dropping of events or blocking.

Solution: Back pressure where the producer and consumer negotiate. 122

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Back pressure, where the producer and consumer negotiate the flow rate dynamically, is the only way to avoid these scenarios.

Back pressure allows strategic management of event flows.

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With a system using backpressure for all flows, it's possible to add global flow control and also strategically decide when you must drop events or take other action.





Logical evolution of Rx. More focus on possiblyinfinite streams of data. 124

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Like Rx, RS uses functional transformations to manipulate the data. It puts slightly more emphasis on the idea of streams (possibly infinite) rather than an event loop.

Akka Streams: a higher-level abstraction implemented with Akka Actors. 125

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We're realizing that Actors are a low-level primitive and Actor systems can become unwieldy. Typesafe thinks that higher-level abstractions, like reactive streams, implemented on low-level concurrency systems, like Actors, will be the way to go for most future systems. Other implementations of RS include RxJava.

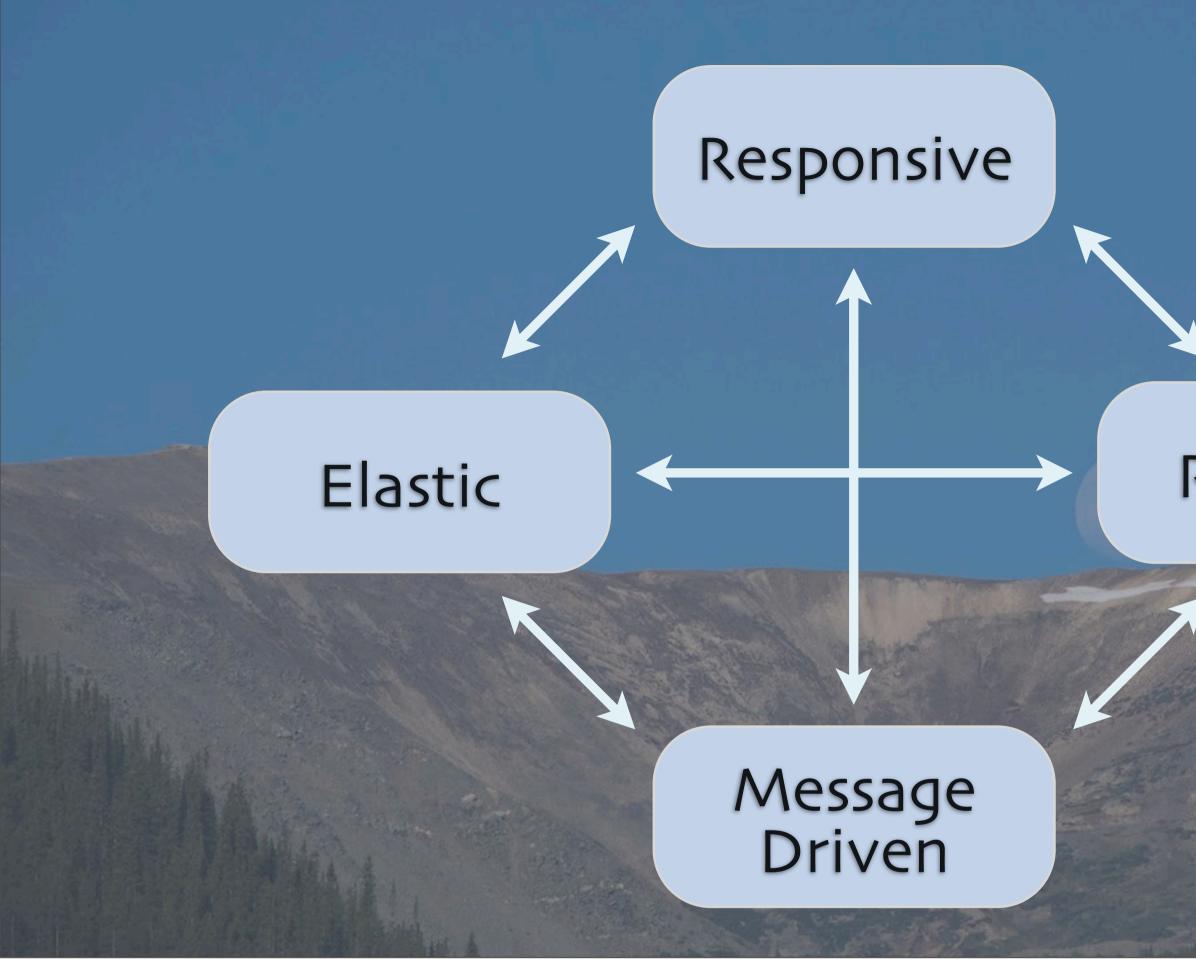
Recap

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Four required properties for highly-available, resilient, and scalable services:

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Resilient

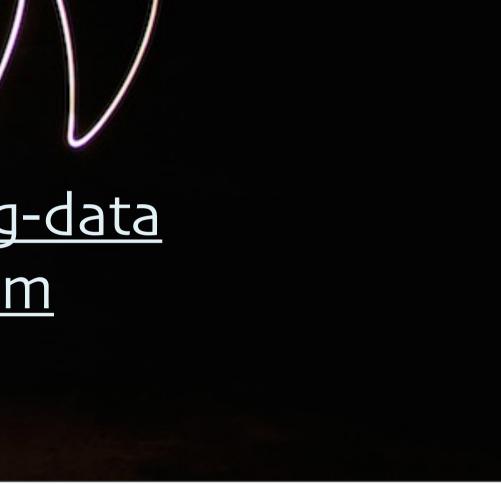


<u>http://typesafe.com/reactive-big-data</u> <u>dean.wampler@typesafe.com</u>

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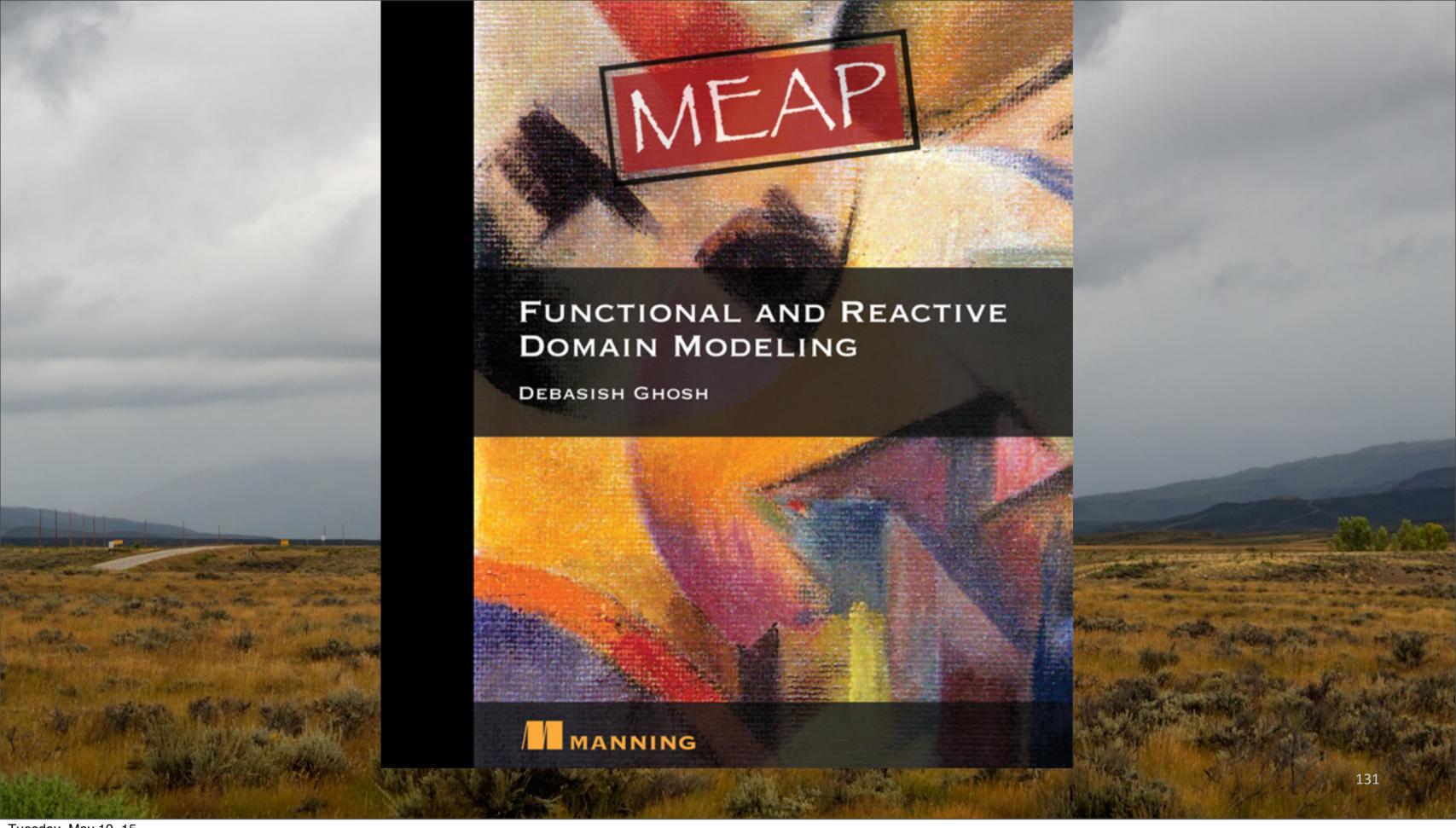
My primary role at Typesafe is addressing the Big Data market. We're now rolling out commercial support for Spark in non-Hadoop environments and we have other projects in the works. Talk to me if you're interested in what we're doing.



References

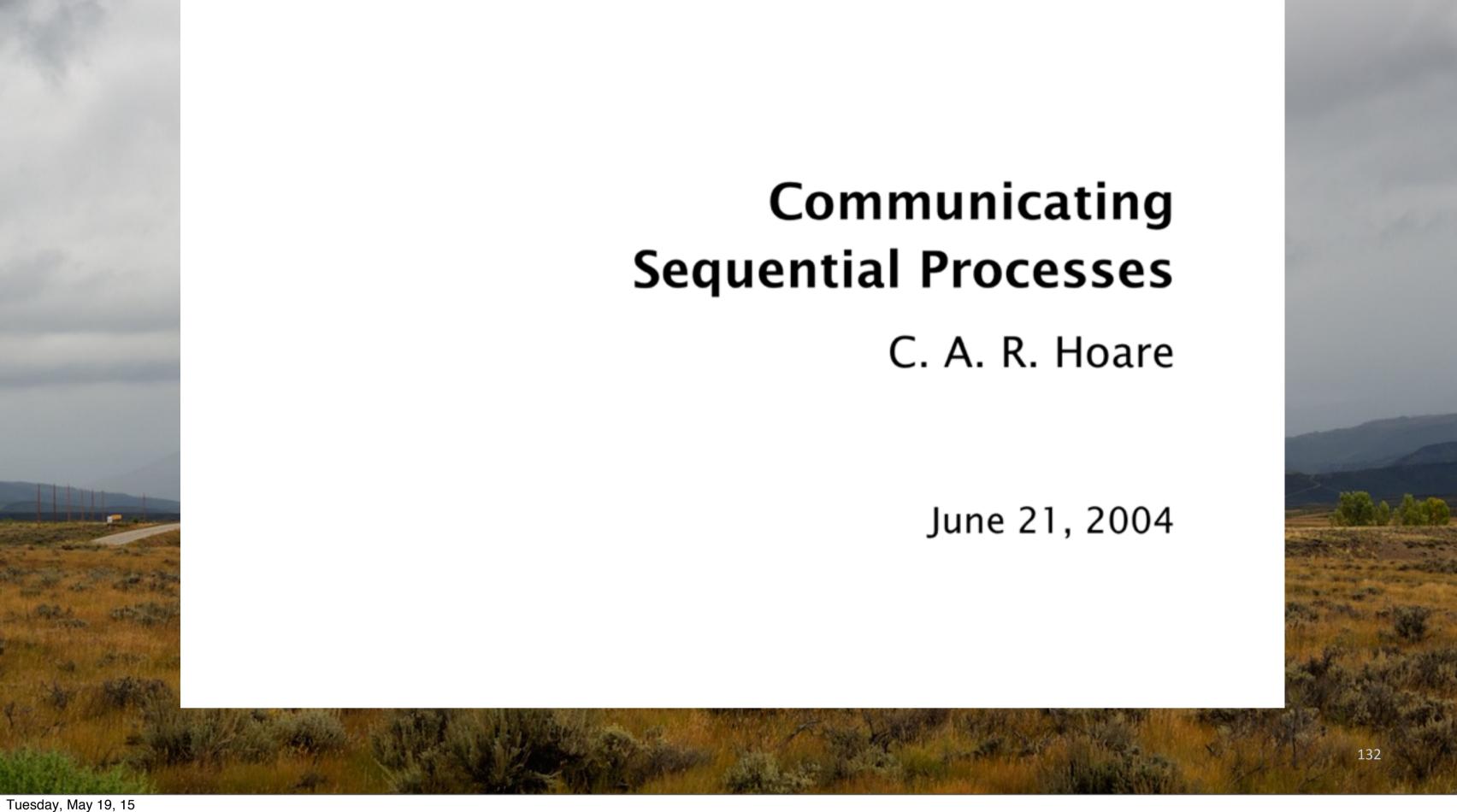
Tuesday, May 19, 15 See also links earlier in the presentation.





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Lots of interesting practical ideas for combining functional programming and reactive approaches to class Domain-Driven Design by Eric Evans.



Hoare's book on CSP, originally published in '85 after CSP had been significantly evolved from a programming language to a theoretical model with a well-defined calculus. The book itself has been subsequently refined. The PDF is available for free.

The Theory and Practice of Concurrency

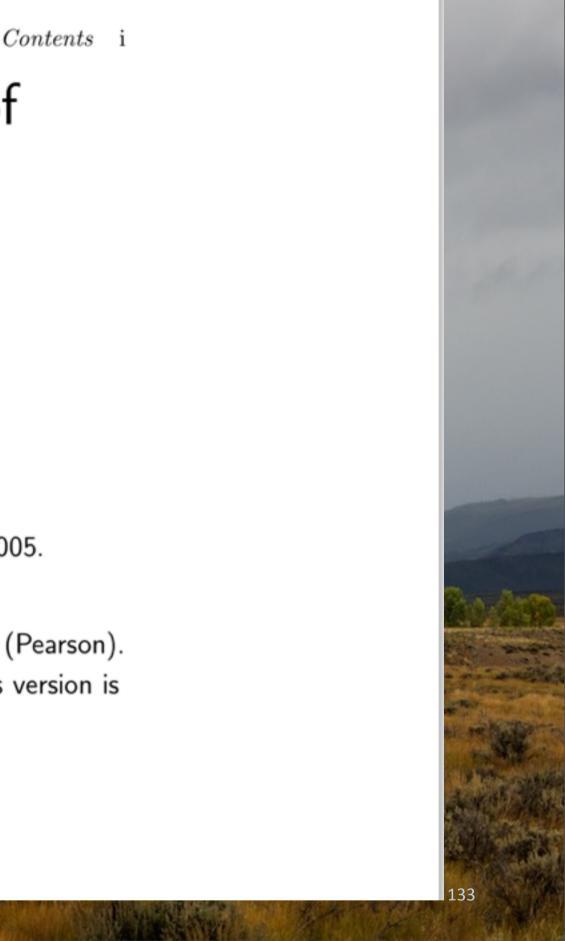
A.W. Roscoe

Published 1997, revised to 2000 and lightly revised to 2005.

The original version is in print in April 2005 with Prentice-Hall (Pearson). This version is made available for personal reference only. This version is copyright (©) Pearson and Bill Roscoe.

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Modern treatment of CSP. Roscoe helped transform the original CSP language into its more rigorous, process algebra form, which was influenced by Milner's Calculus of Communicating Systems work. This book's PDF is available free. The treatment is more accessible than Hoare's book.



PROGRAMMING DISTRIBUTED COMPUTING SYSTEMS

A Foundational Approach

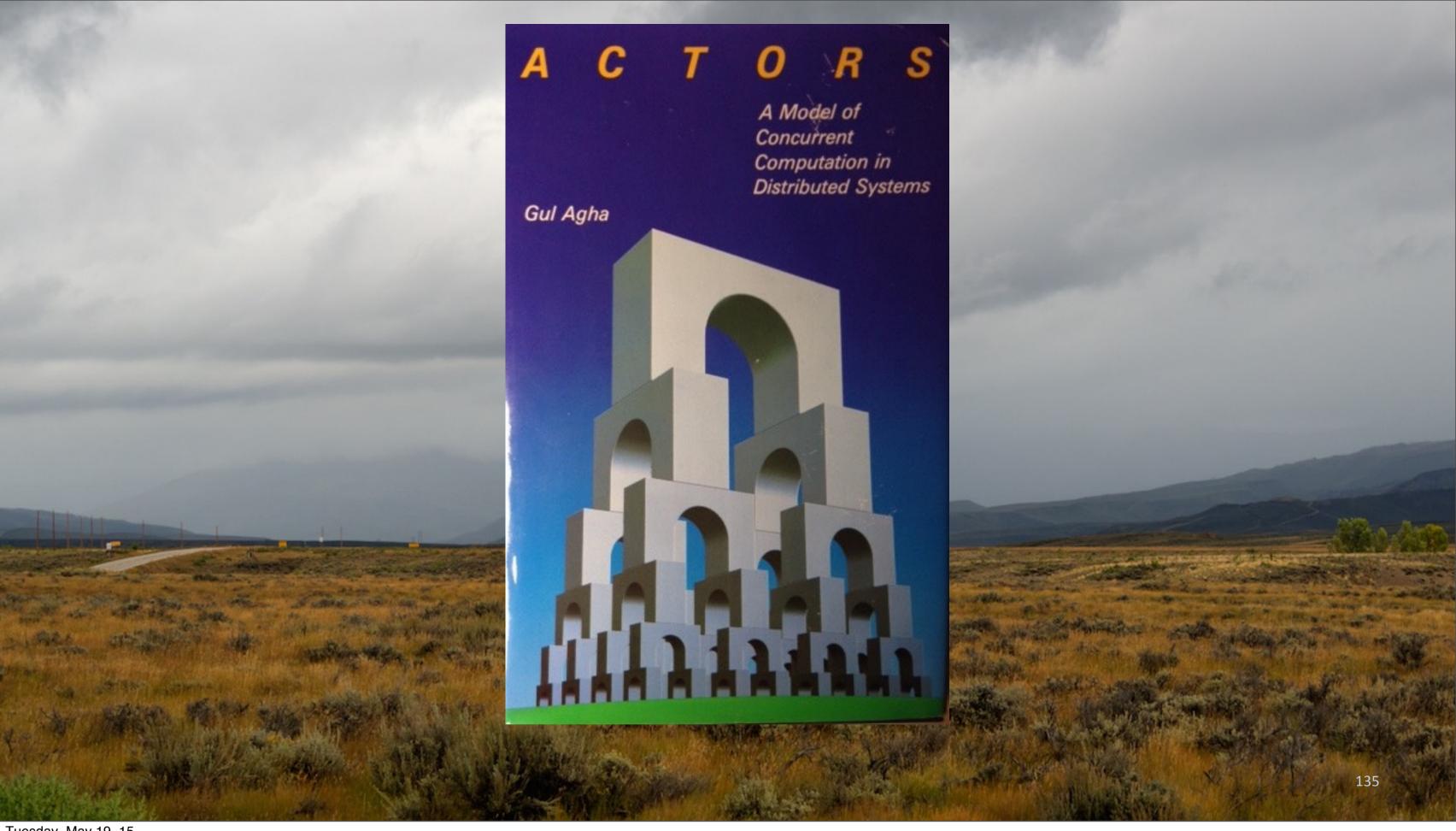
CARLOS A. VARELA



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A survey of theoretical models of distributed computing, starting with a summary of lambda calculus, then discussing the pi, join, and ambient calculi. Also discusses the actor model. The treatment is somewhat dry and could use more discussion of real-world implementations of these ideas, such as the Actor model in Erlang and Akka.





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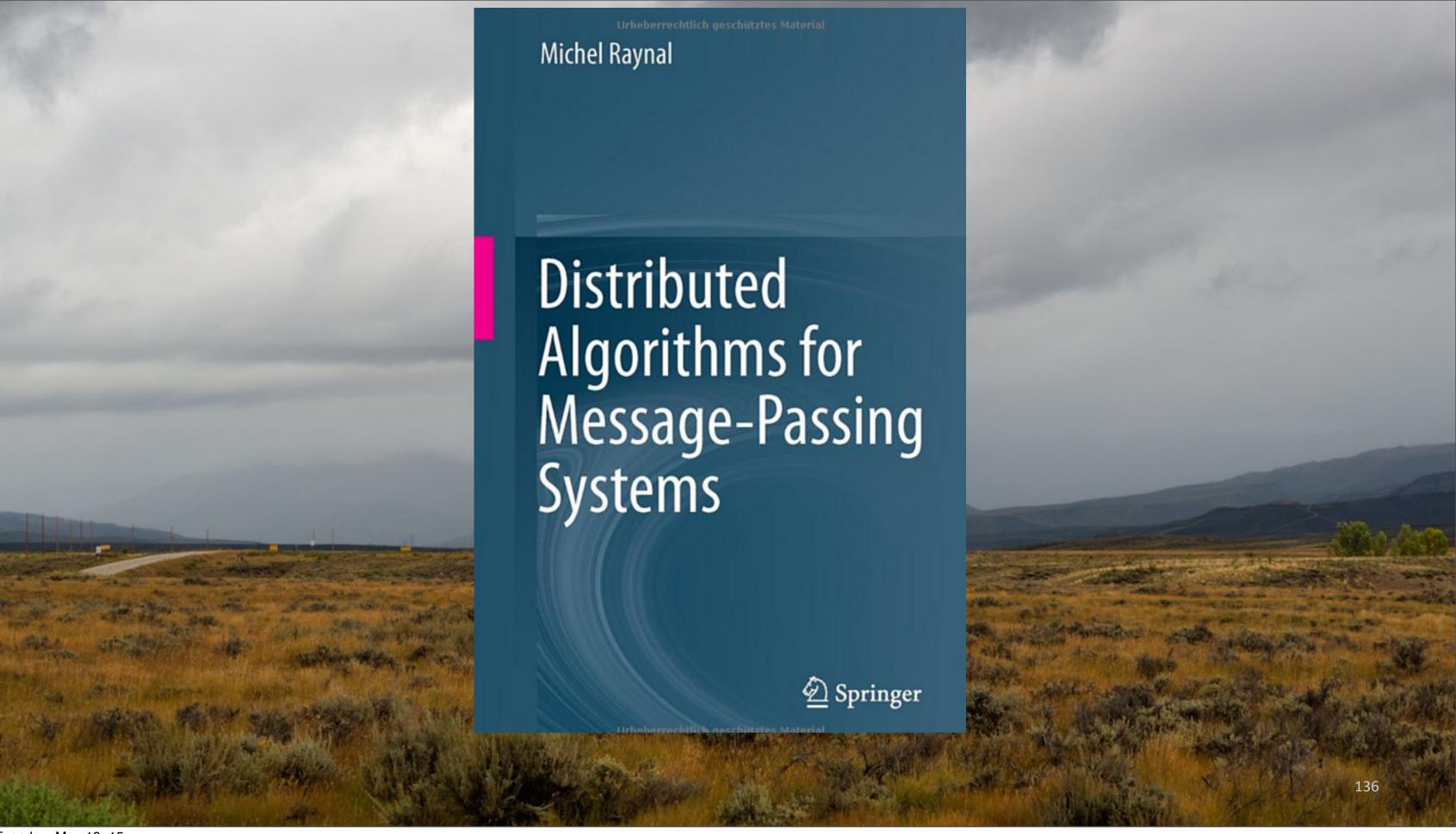
Gul Agha was a grad student at MIT during the 80s and worked on the actor model with Hewitt and others. This book is based on his dissertation.

It doesn't discuss error handling, actor supervision, etc. as these concepts .

His thesis, http://dspace.mit.edu/handle/1721.1/6952, the basis for his book, http://mitpress.mit.edu/books/actors

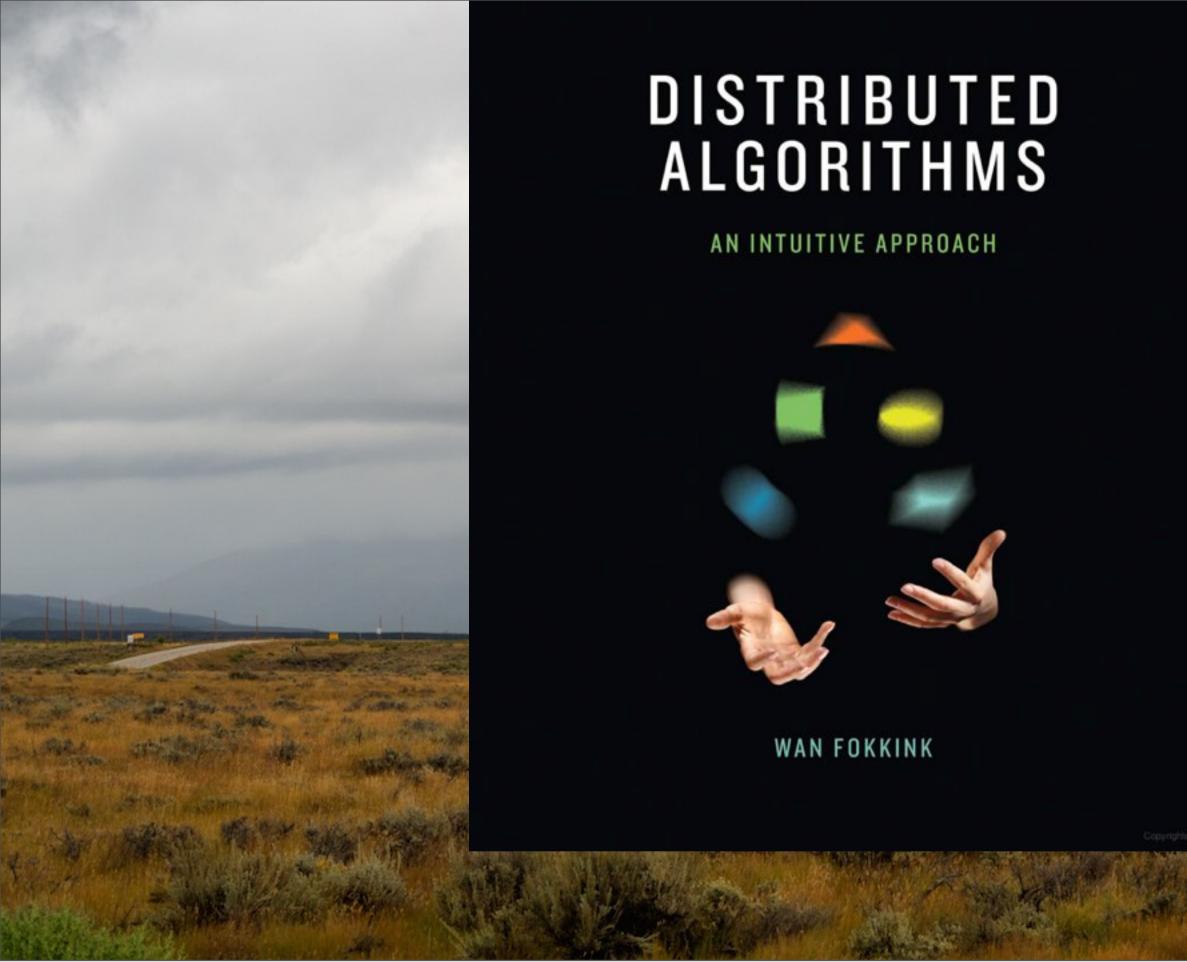
See also Paper for a survey course with Rajesh Karmani, <u>http://www.cs.ucla.edu/~palsberg/course/cs239/papers/</u> <u>karmani-agha.pdf</u>

<u>://mitpress.mit.edu/books/actors</u> alsberg/course/cs239/papers/



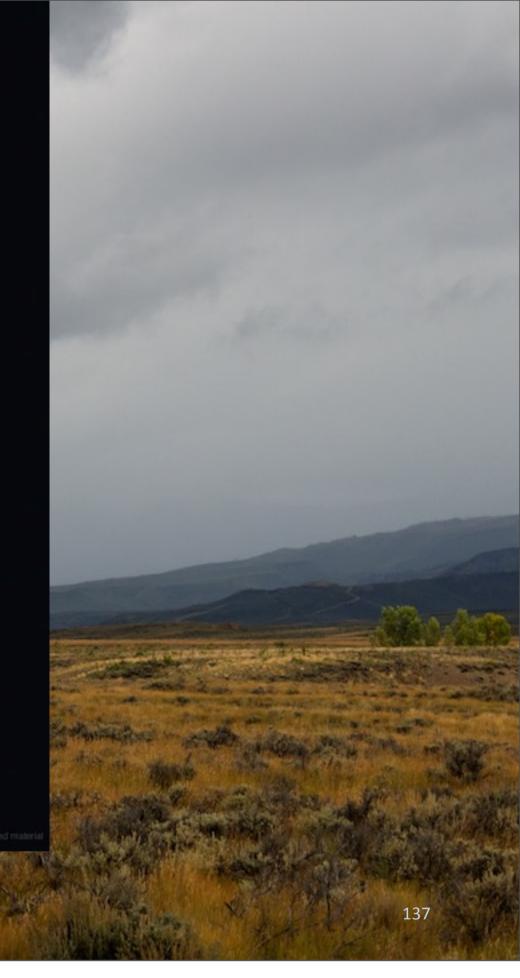
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Survey of the classic graph traversal algorithms, algorithms for detecting failures in a cluster, leader election, etc.



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A less comprehensive and formal, but more intuitive approach to fundamental algorithms.



Christian Cachin Rachid Guerraoui Luís Rodrigues

Introduction to

Reliable and Secure Distributed Programming

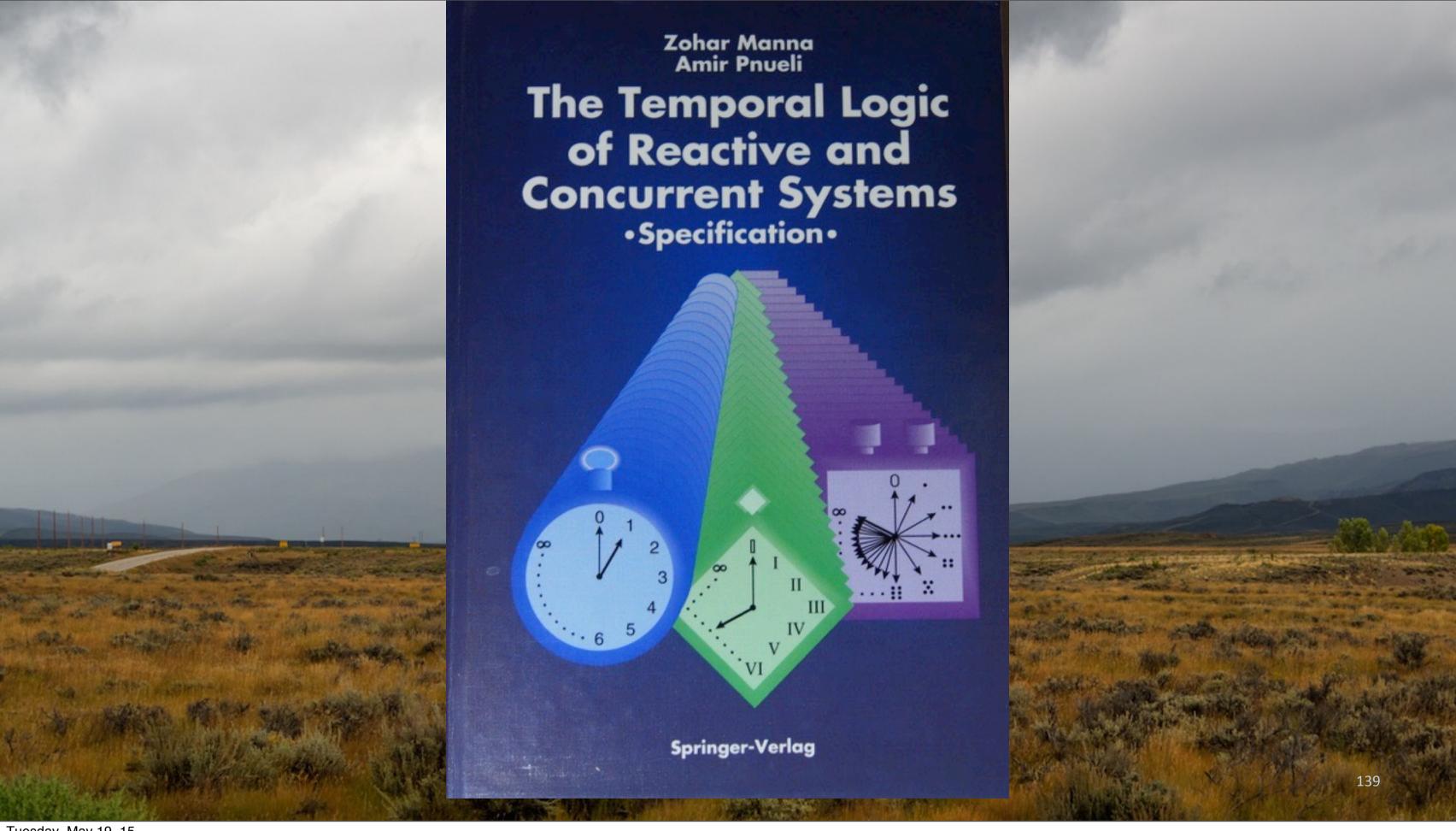
Second Edition

 $\stackrel{{}_{\scriptstyle{\frown}}}{\underline{\bigcirc}}$ Springer

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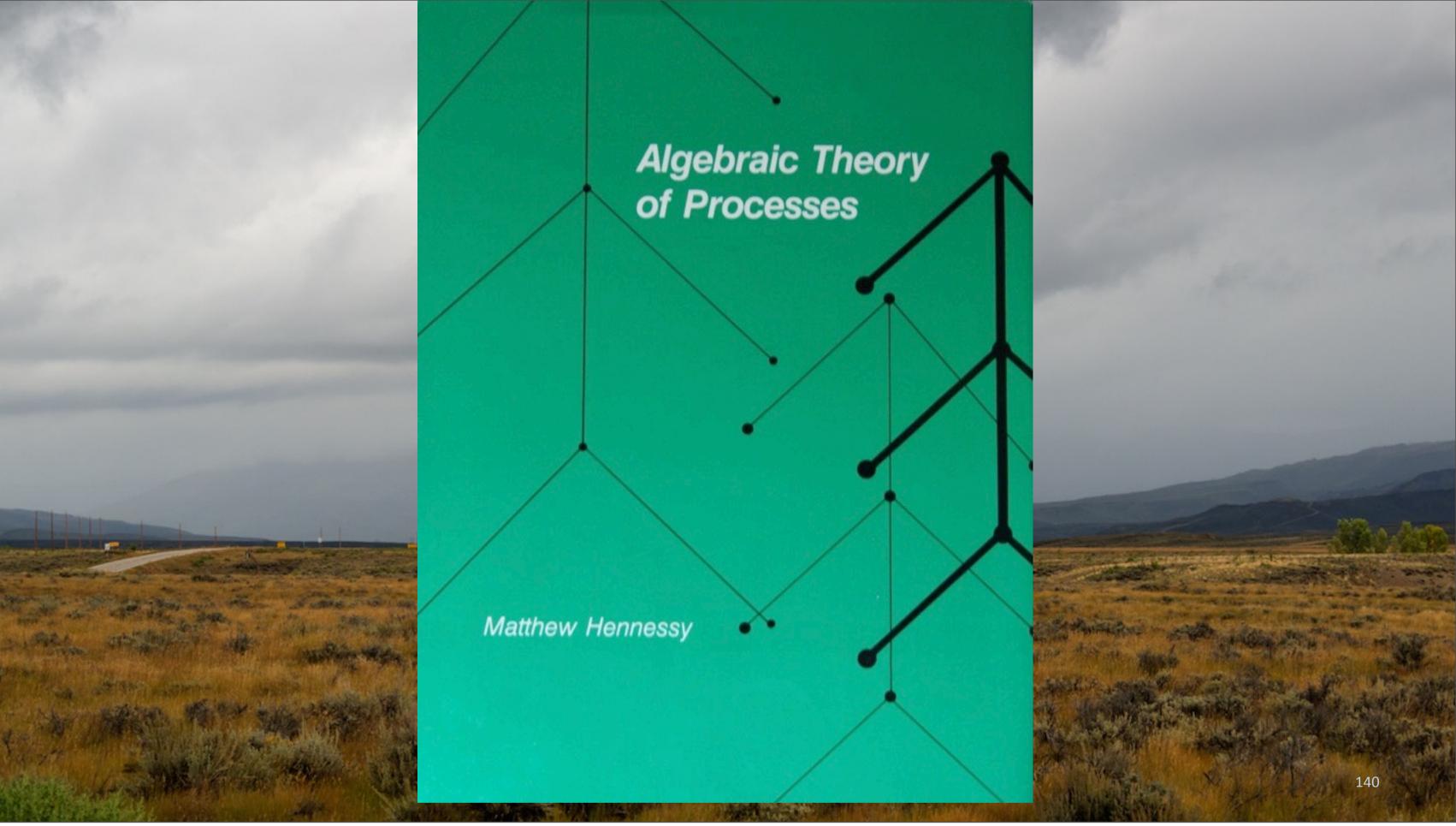
Comprehensive and somewhat formal like Raynal's book, but more focused on modeling common failures in real systems.





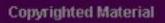
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1992: Yes, "Reactive" isn't new ;) This book is lays out a theoretical model for specifying and proving "reactive" concurrent systems based on temporal logic. While its goal is to prevent logic errors, It doesn't discuss handling failures from environmental or other external causes in great depth.



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1988: Another treatment of concurrency using algebra. It's not based on CSP, but it has similar constructs.



DISTRIBUTED COMPUTING

through

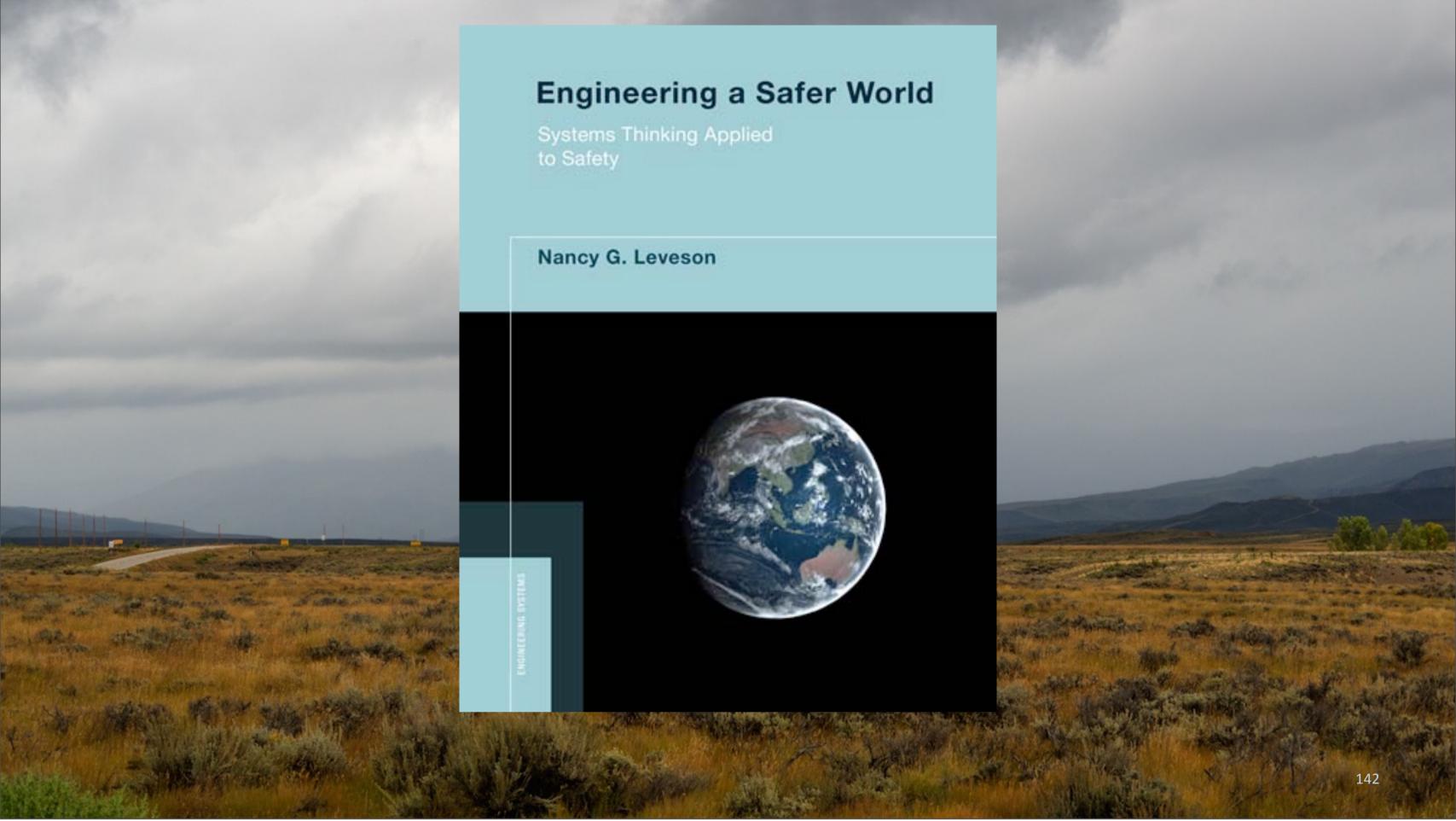
COMBINATORIAL TOPOLOGY



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A recent text that applies combinatorics (counting things) and topology (properties of geometric shapes) to the analysis of distributed systems. Aims to be pragmatic for real-world scenarios, like networks and other physical systems where failures are practical concerns.





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<u>http://mitpress.mit.edu/books/engineering-safer-world</u> Farther afield, this book discusses safety concerns from a systems engineering perspective.